



Leica TPS1200 RoadRunner Tunnel Technical Reference Manual

Version 2.0
English

- when it has to be **right**

Leica
Geosystems

Introduction

Purchase

Congratulations on the purchase of a RoadRunner Tunnel application.



To use the product in a permitted manner, please refer to the detailed safety directions in the User Manual.

Product identification

The type and serial number of your product are indicated on the type plate. Enter the type and serial number in your manual and always refer to this information when you need to contact your agency or Leica Geosystems authorized service workshop.

Type: _____

Serial No.: _____

Symbols

The symbols used in this manual have the following meanings:

Type	Description
	Important paragraphs which must be adhered to in practice as they enable the product to be used in a technically correct and efficient manner.

Trademarks

- Windows and Windows CE are a registered trademark of Microsoft Corporation
 - CompactFlash and CF are trademarks of SanDisk Corporation
 - Bluetooth is a registered trademark of Bluetooth SIG, Inc
- All other trademarks are the property of their respective owners.

Table of Contents

In this manual

Chapter		Page
1	Introduction	6
1.1	Overview	6
1.2	Basic Terms	8
1.3	Elements for Tunnel Stake Out and Check Measurements	11
	1.3.1 Tunnel Face	11
	1.3.2 Tunnel Profiles	13
1.4	Shifts	17
	1.4.1 Centre Line Shifts	18
	1.4.2 Design Profile Shifts	20
2	Getting Started	22
2.1	Preparing Design Data	22
	2.1.1 Tunnel Centreline	23
	2.1.2 Design Profiles	24
	2.1.3 Data transfer to sensor	27
2.2	Using the On-Board Application	28
	2.2.1 Selecting the Application	29
	2.2.2 RoadRunner Begin	31
	2.2.3 RoadRunner Tunnel Setup	33

3	Checking and Measuring the Tunnel	36
3.1	Overview	36
3.2	Checking Profiles	37
3.2.1	Creating a Task	37
3.2.2	Checking the Profile	38
3.3	Scanning Profiles	42
3.3.1	Defining Profiles to Scan	43
3.3.2	Scan Limits	46
3.3.3	Defining Discrete Points to Measure	50
3.3.4	Making a Scan	51
4	Setting Out the Tunnel	56
4.1	Overview	56
4.2	Setting Out the Tunnel Face	57
4.2.1	Creating a Task	61
4.2.2	Setting Out the Point	62
4.3	Setting Out a Tunnel Profile	68
4.3.1	Creating a Task	69
4.3.2	Setting Out the Point	70
5	Project and Job Management	78
5.1	Overview	78
5.2	Selecting a Project	81
5.2.1	Overview	81
5.2.2	Browse for Existing Project	82
5.2.3	Resuming the Last Task	83
5.3	Creating a New Project	84
5.4	Deleting a Project	86
5.5	Editing a Project	88

6	Tunnel Job	90
6.1	Overview	90
6.2	Design Data	91
6.2.1	Horizontal and Vertical Alignments	91
6.2.2	Design Profiles	92
6.2.3	Layers	93
6.3	Tasks	94
6.3.1	Creating a New Task	95
6.3.2	Working with Shifts	99
6.4	Viewing and Editing the Design Data	102
6.4.1	Overview	102
6.4.2	Viewing the Design Data	104
6.4.3	Editing the Design Data	110
7	Configuration	112
7.1	Overview	112
7.2	Tunnel Configuration General Page	114
7.3	Tunnel Configuration Check Page	119
7.4	Tunnel Configuration Scan Page	121
7.5	Tunnel Configuration Info and Plot Page	123
7.5.1	Defining the Info Page Display	126
7.6	Tunnel Configuration Logfile Page	130
Index		132

1 Introduction

1.1 Overview

Description

The RoadRunner Tunnel application is an "add-on" component to the System 1200 RoadRunner application. The tunnel application allows the user to perform tunnel specific survey tasks.

Functionality

The application consists of two main functions:

- **Check Tunnel** for checking a built or excavated tunnel with a tunnel design;
 - **Stake Tunnel** for setting out tunnel features during construction.
-

Check Tunnel

Each function consists of two main tasks, in the case of Check Tunnel, these tasks are:

- **Check Profile** for measuring any point in the tunnel and comparing the measured point with the theoretical design point.
 - **Scan Profile** for measuring profiles of the tunnel.
-

Stake Tunnel

The Stake Tunnel function consists of:

- **Stake Face**, a task that allows setting out at the point of excavation.
 - **Stake Profile** for setting out any point of the tunnel at a given chainage.
-

LandXML data format

The centre line of the tunnel may be imported for use on-board the sensor using the industry standard LandXML data format or in formats exported from a number of other tunnel design packages using the Design to Field component of the Leica Geo Office application.

Refer to chapter "2.1.1 Tunnel Centreline" for more information regarding the import of centre line data.

Tunnel design profiles

Tunnel design profiles may be created using the tunnel profile editor PC application. This application is integrated into the Design to Field component.

Keys

The **ALL (F1)**, **DIST (F2)**, **REC (F3)**, **<PAGE (F5)** and **PAGE> (F6)** keys have the same functionality as throughout the rest of System 1200.

1.2

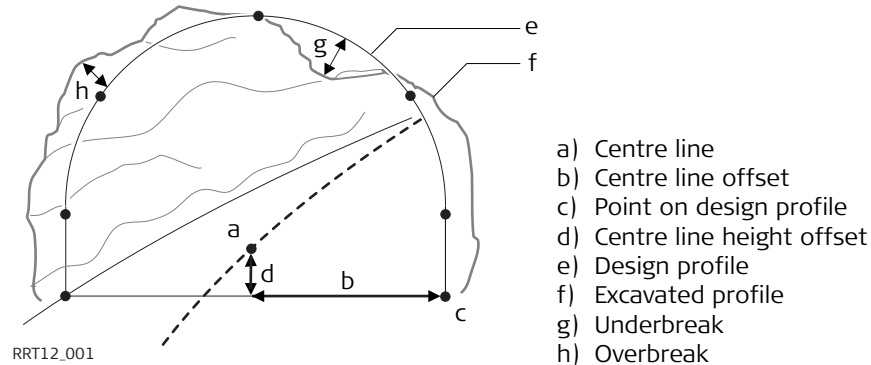
Basic Terms

Basics introduced

In order to make the following chapters on staking and checking tunnels easier to understand, the basics are introduced in this chapter.

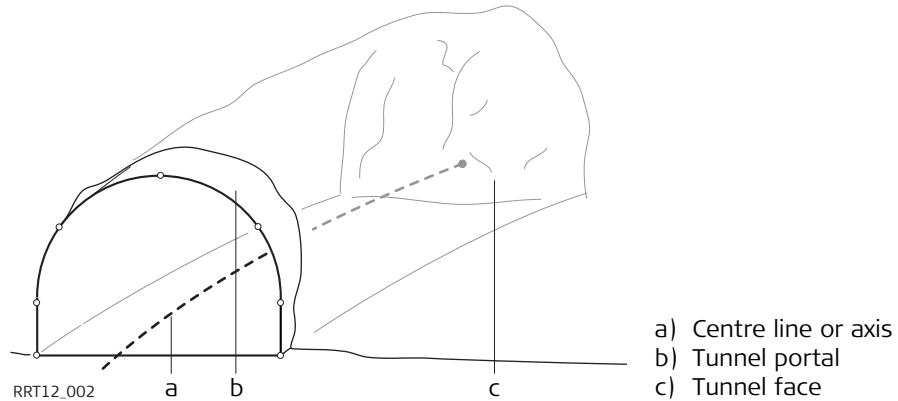
Please be aware that the terminology or workflow used on different construction sites may vary from the one used in this manual, however, basic principles remain the same.

Technical terms

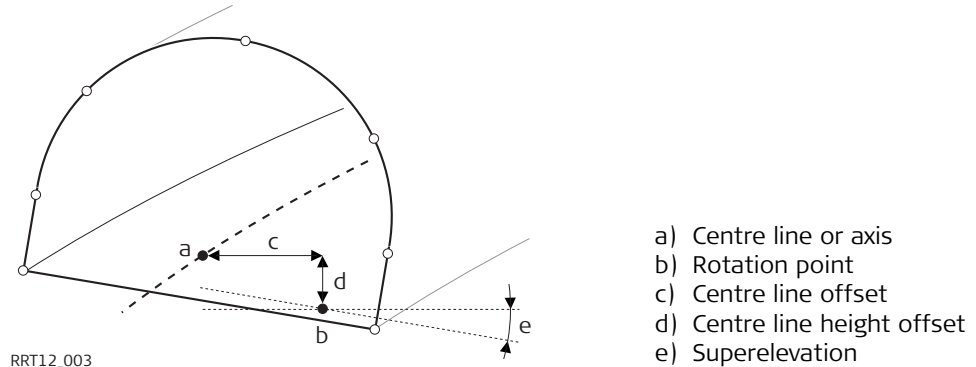


RRT12_001

3D View



Superelevation



Refer to Chapter 3, RoadRunner Technical Reference manual for additional terms.

Technical Terms

Technical Term	Description
Centre line	Geometric alignment in two or three dimensions to which all design elements of the project are referenced.
Chainage or station	The cumulative distance along the centre line, frequently but not always starting at zero.
Design Profile	Geometric description of the designed shape of the cross-section of the tunnel. The design profile may contain straight or curve elements.
Excavated Profile	Shape of the cross-section of the tunnel that has been excavated.
Underbreak	When the excavated profile is inside the design profile, the underbreak is the perpendicular distance between the design profile and the excavated profile.
Overbreak	When the excavated profile is outside of the design profile, the overbreak is the perpendicular distance between the design profile and the excavated profile.
Tunnel Portal	The open end of a tunnel.
Tunnel Face	The point where the excavated tunnel meets existing terrain.
Superelevation	Angle of rotation of a design profile, used to take into account the velocity of a moving vehicle through a curve.
Rotation Point	The point about which the design profile is rotated. This point may or may not coincide with the centre line.

1.3

Basic stake out and check elements

1.3.1

Staking Tunnel Faces

Horizontal and vertical offsets

Elements for Tunnel Stake Out and Check Measurements

In general there are two different basic stake out and check elements within a tunnel:

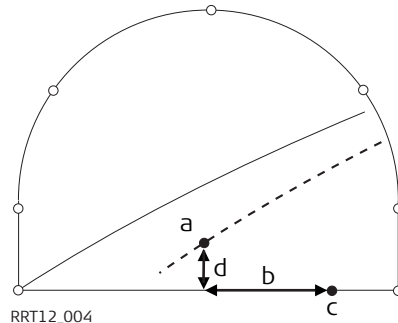
- Tunnel Face
- Tunnel Profile

Tunnel Face

It is usually required to stake out the tunnel face to indicate the position to excavate when certain tunnelling methods are used (e.g. Drill and Blast or excavation using a roadheader).

The points to stake on the tunnel face may be defined in various ways:

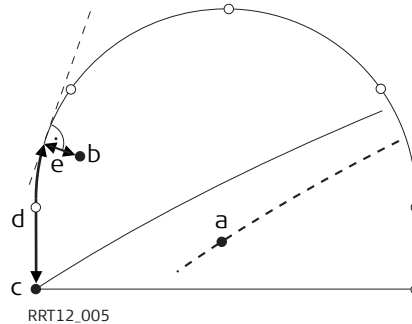
By horizontal and vertical offsets with respect to the centre line:



- a) Centre line
- b) Point on tunnel face to stake
- c) Centre line offset
- d) Centre line height offset

Distance along profile

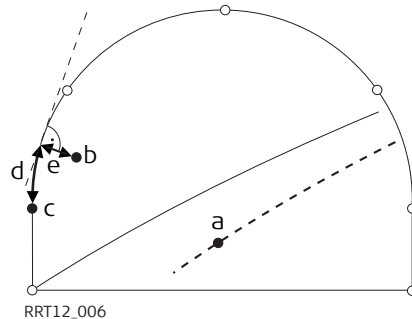
By the distance from the start of the design profile and an offset from the design profile.



- a) Centre line
- b) Point on tunnel face to stake
- c) Point defining start of design profile
- d) Distance from start of design profile
- e) Offset perpendicular to design profile

Distance along a particular element

By the distance along a particular element of the design profile and an offset from the element.



- a) Centre line
- b) Point on tunnel face to stake
- c) Element of design profile to stake
- d) Distance from start of design profile element
- e) Offset perpendicular to design profile

1.3.2

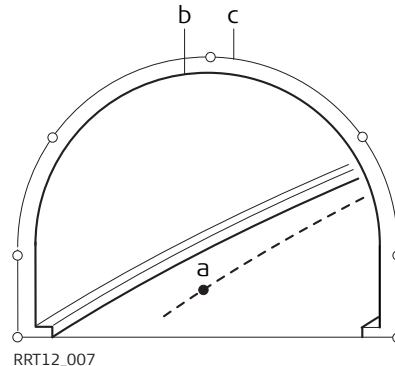
Tunnel Profiles

Staking tunnel profiles

Tunnel Profiles are normally staked after excavation to indicate the position of tunnel design elements or services such as lighting or ventilation.

Basic terms

Usually a tunnel under construction is designed and built in various stages such that a given chainage can have various design profiles (e.g. shotcrete, final lining...). Each design profile is called a layer.



- a) Centre line or axis
- b) Final lining
- c) Shotcrete

Working areas

A tunnel profile is defined by its chainage and the design profile assigned to that chainage. Points to stake on any layer of the design profile may be defined using the same methods as those used to stake the tunnel face.

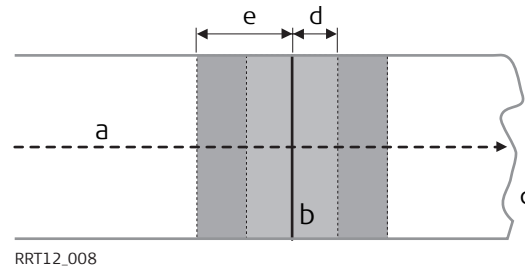
When staking out in a tunnel, it is normally the case that the excavated profile does not coincide exactly with the design profile. In these cases, the irregular form of the excavated profile may mean that it is not possible to stake a particular point at a particular chainage from a given instrument position (e.g. in a tight curve).

For this reason, a tight tolerance may be used to determine whether a staked point be accepted or not, the stake out process will stop once a measured point is within the tight tolerance limits.

In extreme cases where the instrument positions itself very far away from the point to stake, it may not be worth trying to stake the point. In this case a bailout tolerance may be introduced. If a measured point is outside of the bailout tolerance during the stake out iteration process, the stake out of the point is abandoned.

The bailout tolerance may also be exceeded if an obstruction such as plant machinery is situated between the measurement sensor and the point being measured.

Plan view



RRT12_008

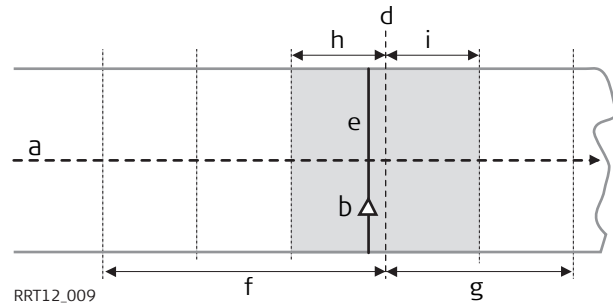
- a) Centre line
- b) Profile to stake
- c) Tunnel face
- d) Tight tolerance
- e) Bailout tolerance

Measuring tunnel profiles

Tunnel Profiles are normally measured after excavation to compare the excavated profile with the design profile during the excavation phase of the project or for quality control checks of the built tunnel.

When measuring tunnel profiles, it is possible to scan various profile from one instrument position. The profiles to scan are defined with respect to a defined chainage. Profiles may be scanned at a given forward and back interval within a given forward and back distance from the defined profile.

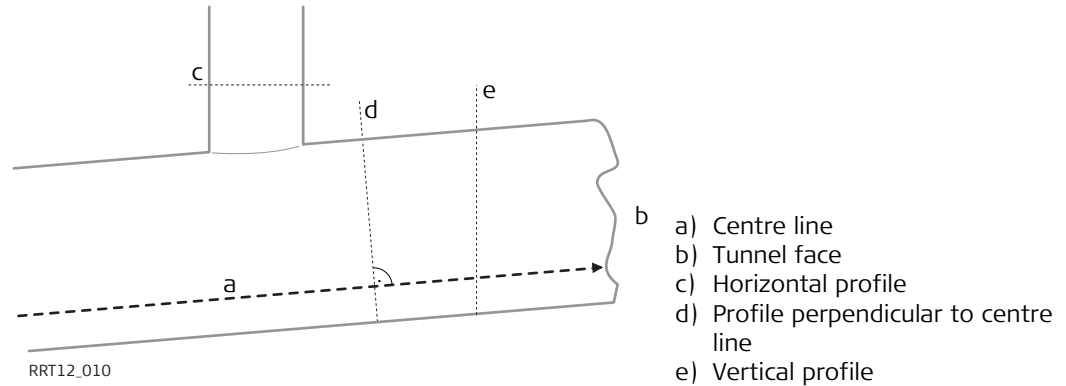
Plan view



- a) Centre line
- b) Instrument position
- c) Tunnel face
- d) Defined profile to scan
- e) Instrument profile
- f) Back distance
- g) Forward distance
- h) Back interval
- i) Forward interval

Profile view

Tunnel profiles may be measured vertically, horizontally or perpendicular to the tunnel centre line.



1.4

General



Shifts

When working on site, it is often the case that design data does not match the measured data. For example, an existing road surface that should intersect with the design surface may be 15 cm higher than the plans indicate. To guarantee a smooth intersection, this difference has to be distributed over the remaining 100 m of paving. To handle these situations, RoadRunner allows the possibility of adding shifts to the existing design data. A shift is applied when selecting the element to stake out/check.

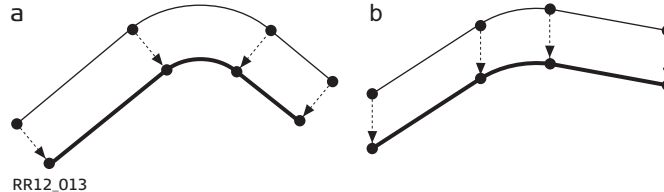
Shifts do not change the stored design. They are applied temporarily for stake out purposes.

1.4.1

Centre Line Shifts

Horizontal and vertical shifts

Horizontal shifts are always perpendicular to the centre line whereas vertical shifts are applied along the plumb line.



RR12_013

- a) Horizontal alignment with constant shift (Plan View)
- b) Vertical alignment with constant shift (Profile View)

Constant and linear shifts are supported

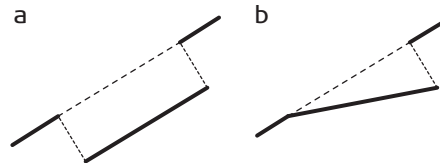
For both horizontal and vertical shifts two different types are available (can be applied):

Constant:

The shift remain the same from its start chainage or station to the end chainage or station.

Linear:

The shift is linearly interpolated along the chainage or station.

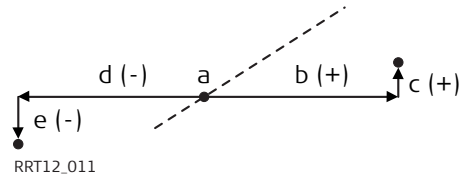


RRT12_025

- a) Constant shift
- b) Linear shift

Sign convention

The sign convention for design shifts is identical to that used for centre line offset and height shifts difference.



- a) Centre line
- b) Positive horizontal shift
- c) Positive vertical shift
- d) Negative horizontal shift
- e) Negative vertical shift

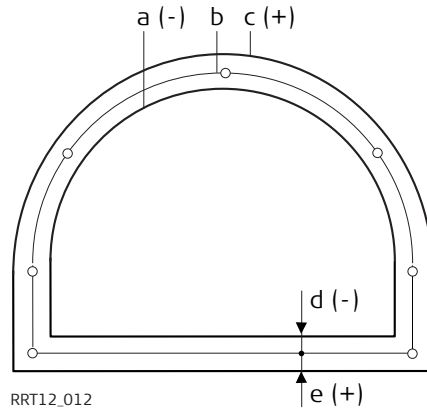
1.4.2

Design Profile Shifts

Profile shift

A shift may be applied to the design profile. The shift is applied perpendicularly to the design profile at any point along the design profile.

A positive shift will increase the size of the profile, a negative shift will decrease the size of the profile.



RRT12_012

- a) Design profile with negative shift
- b) Original design profile
- c) Design profile with positive shift
- d) Negative shift
- e) Positive shift

2

Getting Started

2.1

Preparing Design Data

Downloads section

The tunnel design data may be imported for use on-board the sensor using the industry standard LandXML data format or in formats exported from a number of other design packages using the Design to Field component of the Leica Geo Office PC application. Converters are available for more than 15 different design packages.



The latest version of the Design to Field importers may be found in the Downloads section of the Leica Geosystems web site at http://www.leica-geosystems.com/s-e/en/downloads/lgs_page_catalog.htm?cid=4948

2.1.1

Tunnel Centreline

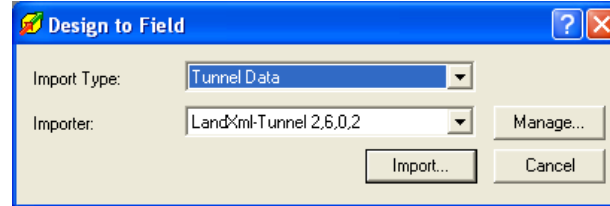
Basics

The tunnel centre line may be defined in two or three dimensions. A 3-dimensional centre line is required if design profiles are to be used.

Design to field



To import a centre line using the Design to Field component select the **Tools/Design to Field** option of the Leica Geo Office PC application.



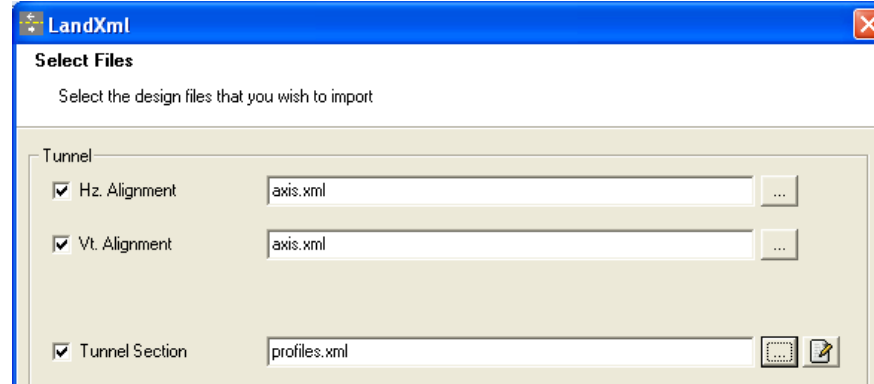
For general information about Design to Field please refer to the Leica Geo Office Manual or Online Help.

2.1.2

Design Profiles

Tunnel design profiles

If tunnel design profiles are available, they may be created using the tunnel profile editor PC application. This application is integrated into the Design to Field converters. Select the files which define the horizontal and vertical alignment and the tunnel profiles:



If you need to create new profiles press the Modify button in the Tunnel Section line to launch the Tunnel Profile Editor. Define the profile and the profile assignments:

Tunnel Profile Editor - C:\RR\Profile.xml

File About

Design Profiles

Name	Description	State
CP Exc	Description	Proposed
Inner Exc	Description	Proposed
Outer Exc	Description	Proposed
Aline CP	Description	Proposed
Aline Exc	Description	Proposed

CP Exc Description Proposed

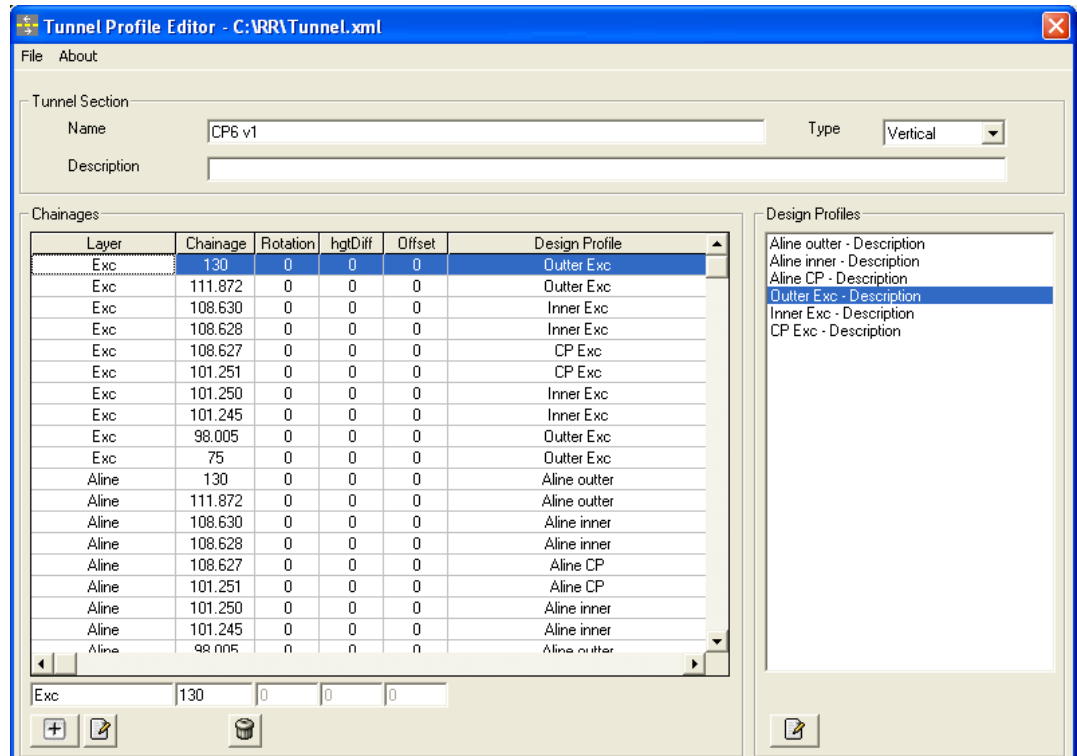
+ [Icon] [Icon]

Elements

Id	Type	X Start	Y Start	X End	Y End	Description	Length	Radius	X Center	Y Center
1	Line	0	3.707	0.927	3.707		0.927000			
2	Line	0.927	3.707	1.479	3.632		0.557072			
3	Line	1.479	3.632	2.207	2.808		1.099527			
4	Curve	2.207	2.808	3.106	1.128			3.160000	-0.000025	0.546443
5	Line	3.106	1.128	3.224	0.499		0.639973			
6	Line	3.224	0.499	3.540	0.499		0.316000			
7	Line	3.540	0.499	3.540	-0.786		1.285000			
8	Line	3.540	-0.786	3.274	-0.786		0.266000			
9	Curve	3.274	-0.786	2.920	-2.493			7.189000	-3.890291	-0.190466
10	Line	2.920	-2.493	2.920	-2.493		5.840000			
11	Curve	2.920	-2.493	2.924	-0.786			7.189000	-3.890291	-0.190466

1 Line 0 3.707 0.927 3.707 0.927000

+ [Icon] [Icon]



Step through the wizard and open the Design to Field viewer by clicking Finish on the last page of the wizard. Finally, click the Export button in the viewer to create the tunnel job.

2.1.3

Getting data onboard

Data transfer to sensor

Once the design data have been converted, copy the database files to the DBX folder of the CompactFlash card that will be used on the sensor. The file names are "jobname.x??".

These files are:

- Fixpoint job
- Meas job
- Tunnel job

2.2

Using the On-Board Application

Installation and licencing

The RoadRunner Tunnel application is an "add-on" component of the RoadRunner TPS1200 program. It is necessary that both the RoadRunner and RoadRunner Tunnel applications are loaded on the sensor before starting.

Both the RoadRunner and RoadRunner Tunnel applications are protected. They may be activated through a specific licence key. This licence key may be typed-in either through the Main Menu: Tools...\Licence Keys or, alternatively, the first time the application program is started.

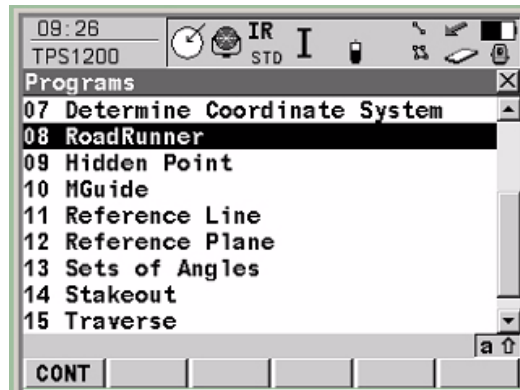
2.2.1

Selecting the Application

Starting RoadRunner Tunnel



1. Select **Main Menu: Programs...**
OR
Press PROG.



2. TPS1200 Programs
Select **RoadRunner** in the menu.
3. **CONT (F1)** to access RoadRunner Begin panel.

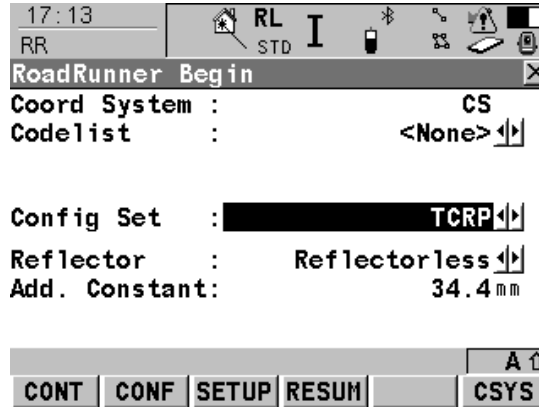
2.2.2

RoadRunner Begin

Positioning the TPS

This screen shows the following:

To select the coordinate system, codelist, configuration set and reflector for the survey.



CONT (F1)

To continue to the next screen.

CONF (F2)

To access the configuration settings.
Refer to "7 Configuration".

SETUP (F3)

To set up an instrument station by determining the station coordinates and orienting the horizontal circle.

RESUM (F4)

To resume the last used and stored task.
This is a recommended feature when using Advanced mode.

CSYS (F6)

To change the current coordinate system.

Field	Description of Field
Coord System	Output. The active coordinate system. Use CSYS (F6) to change the coordinate system. Tunnel jobs are defined in local grid coordinates. The right coordinate system must be chosen for the tunnel job.
Codelist	Choicelist. The active codelist. All codelists from Main Menu: Manage...\Codelists can be selected.
Config Set	Choicelist. The active configuration set. All configuration sets from Main Menu: Manage...\Configuration Sets can be selected.
Reflector	Choicelist. The reflector currently set in the selected configuration set. All reflectors from 'Main Menu: Manage...\Reflectors' may be selected.
Add. Constant	Output. The additive constant stored with the chosen reflector.

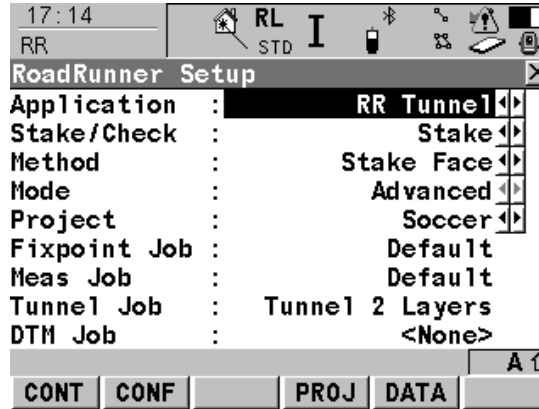
2.2.3

RoadRunner Tunnel Setup

RoadRunner Setup

This screen shows the following:

An overview of the setup information selected for the survey.



CONT (F1)

To continue to the next screen.

CONF (F2)

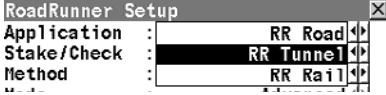
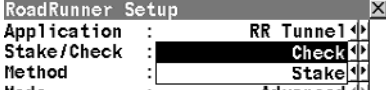
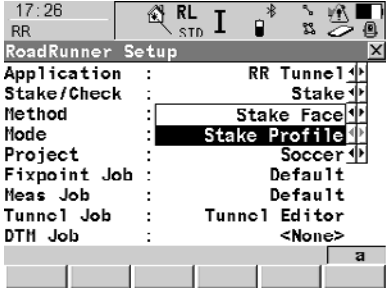
To access the configuration settings.
Refer to "7 Configuration".

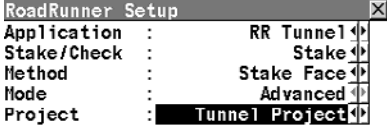
PROJ (F4)

To edit the currently selected project.
Refer to "5 Project and Job Management".

DATA (F5)

To view/edit the data in the tunnel job.
Refer to "6.4 Viewing and Editing the Design Data".

Field	Description of Field
Application	<p>To select the relevant program. This field lists all of the programs that have been loaded into the RoadRunner group. Ensure that RR Tunnel is selected.</p> 
Stake/Check	<p>To select either Stake or Check for the survey.</p> 
Method	<p>To select the relevant method for the survey. All stake/check methods are listed.</p> 

Field	Description of Field
Mode	Set to Advanced automatically and can not be changed in RoadRunner Tunnel. 
Project	To select the relevant project for the survey.
Fixpoint Job	The fixpoint job, as defined by the project.
Meas Job	The measure job, as defined by the project.
Tunnel Job	The tunnel job, as defined by the project.
DTM (Digital Terrain Model) Job	The DTM job, as defined by the project.

3 Checking and Measuring the Tunnel

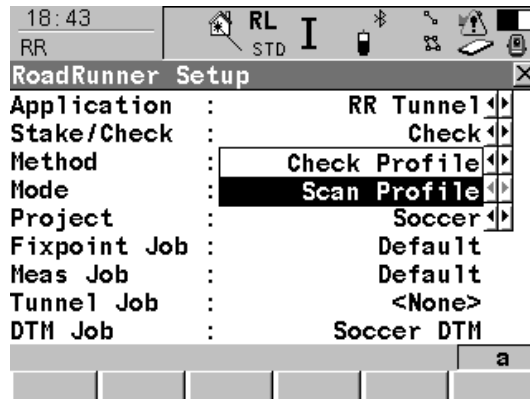
3.1 Overview

Check and measure

The Check Profile and Scan Profile options can be accessed from the RoadRunner Tunnel Setup panel.

The **Check Profile** option allows any point, anywhere in the tunnel to be checked against the design values. If no design profile has been defined in the Tunnel Job, the measured point is analysed with respect to the horizontal and vertical alignment.

The **Scan Profile** option allows profiles of the tunnel, perpendicular to the centre line to be measured. Various profiles may be measured from one instrument position.



3.2

3.2.1

Task management

Checking Profiles

Creating a Task

In order to check a profile, a task needs to be created to define the shifts to be used during the check. More information on shifts can be found in chapter "1.4 Shifts"

17:18
RR

RL STD I

Tasks - Tunnel

Name	Date
REF2_25	06.03.06
REF2_23	06.03.06

CONT NEW EDIT DEL MORE TEMP

A ↑

CONT (F1)

Selects the highlighted task and proceeds to the Check Begin panel.

NEW (F2)

Starts the task wizard.

TEMP (F6)

Creates a temporary task.



More information on creating tasks can be found in chapter "6.3 Tasks".

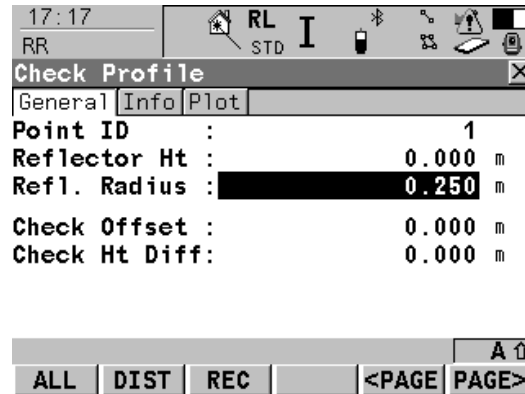
3.2.2

Checking the Profile

Settings

The **Check Profile** dialogue allows any point of the tunnel to be checked against the design values. If no design profile has been defined in the Tunnel Job, the measured point is analysed with respect to the horizontal and vertical alignment.

Enter Information regarding the measured point in the General panel of the Check Profile dialogue.

**Point ID**

The measured point will be recorded with the point ID displayed on the screen.

Reflector Ht

If a reflector is used, the vertical difference between the point to be measured and the point of the reflector pole should be entered.

Check Offset

Applies a horizontal shift perpendicular to the centre line used for comparing to the measured point.

Check Ht Diff

Applies a vertical shift to the centre line used for comparing to the measured point.

The **ALL (F1)**, **DIST (F2)**, **REC (F3)**, **< PAGE (F5)** and **PAGE > (F6)** keys have the same functionality as throughout the rest of System 1200.



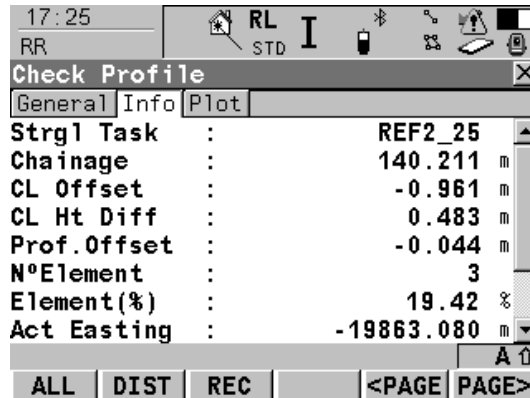
Results

The differences between the measured and design data may be viewed in the Info panel of the **Check Profile** dialogue.

The parameters viewed in the **Info** panel may be configured by the user in the **Info&Plot** page of the application configuration.

The configuration may be accessed using the **CONF (SHIFT-(F2))** key. Refer to chapter "7 Configuration" for more details regarding the application configuration.

In this screen the most important values for checking the measured point against the design are:



CL Offset

The plan distance from the measured point to the horizontal alignment.

CL Ht Diff

The vertical distance between the vertical alignment and the measured point.

Prof. Offset

The perpendicular distance between the measured point and the design profile. A measured point that is located inside of the design profile will always have a negative profile offset.

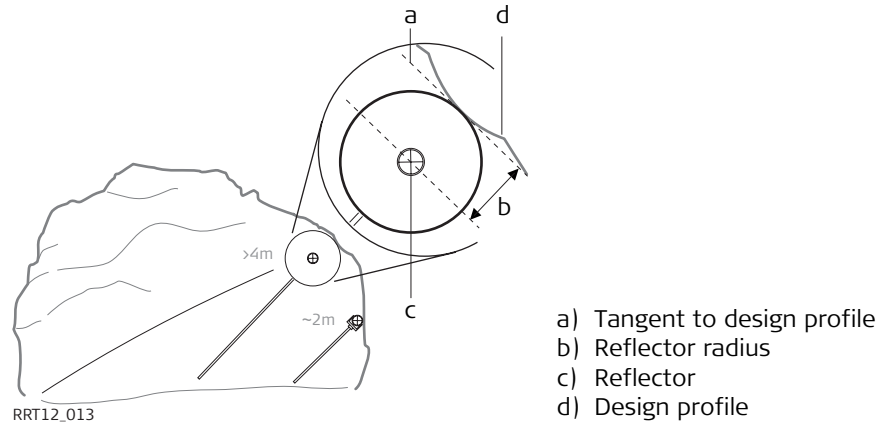
Radial offset

When using a reflector to check a design profile it is important to take into account the reflector radius parameter in the **General** page of the application configuration.

If this parameter is set to **Yes**, the measured point will be projected by a distance equivalent to the radius of the reflector in a direction perpendicular to the tangent of the design profile. If this parameter is set to **No**, the design profile will be compared to the coordinates of the centre of the reflector at the measured position.

If reflectorless measurements are used or no design profile is has been defined, the reflector radius parameter will not be used in the calculation.

The **Plot** panel of the **Check Profile** dialogue displays a plot of the measured point with respect to the design profile.



3.3 Scanning Profiles

Overview

The **Scan Profile** option allows profiles of the tunnel, perpendicular to the centre line to be measured. Various profiles may be measured from one instrument position. The **Scan Profile** option can be selected from the **Tunnel Check** dialogue.

In order to scan profiles, a task must be created and the instrument must be stationed and oriented. Refer to chapter "3.2 Checking Profiles" for more information.

Once the task has been selected and the instrument stationed, the parameters for the scan have to be entered.

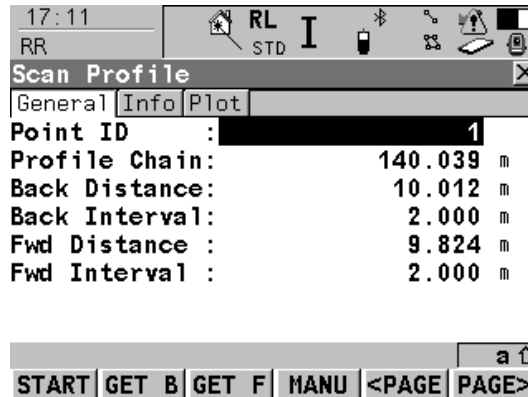
3.3.1

Defining Profiles to Scan

Profile settings

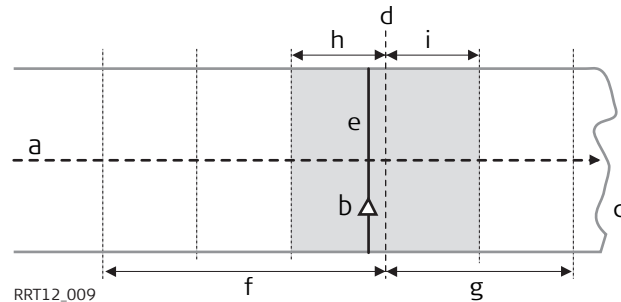
When measuring tunnel profiles, it is possible to scan various profiles from one instrument position. Note that the instrument will always measure the profile in the chainage where the instrument is stationed before measuring additional profiles.

If it is required to measure more than one profile from an instrument position, the profiles to scan are defined with respect to a defined chainage. This defined chainage, **Profile Chain**, may or may not coincide with the chainage at which the instrument is stationed. Profiles may be scanned at a given forward (**Fwd Interval**) and back interval (**Back Interval**) within a given forward (**Fwd Distance**) and back distance (**Back Distance**) from the defined profile.



Planview

A graphical representation of the parameters may be seen below.



- a) Centre line
- b) Instrument position
- c) Tunnel face
- d) Defined profile to scan
- e) Instrument profile
- f) Back distance
- g) Forward distance
- h) Back interval
- i) Forward interval

Defining the Interval

The limits for the profile measurements, forward distance and back distance, may be entered manually in the **General** panel of the **Scan Profile** dialogue or may be measured using the **GET B** and **GET F** keys:

GET B (F2)

Measures a distance from the instrument position and calculates the difference in chainage between the measured point and the chainage of the instrument position. The calculated difference is then set as the **Back Distance**.

GET F (F3)

Measures a distance from the instrument position and calculates the difference in chainage between the measured point and the chainage of the instrument position. The calculated difference is then set as the **Forward Distance**.

Note that the measured point for a back distance must always be at a chainage less than the chainage of the instrument position. The measured point for a forward distance must always be at a chainage greater than the chainage of the instrument position. If these conditions are not met, an error message will be displayed and it will be necessary to redefine the distance.

3.3.2

Scan Limits

Inclusive and exclusive sections

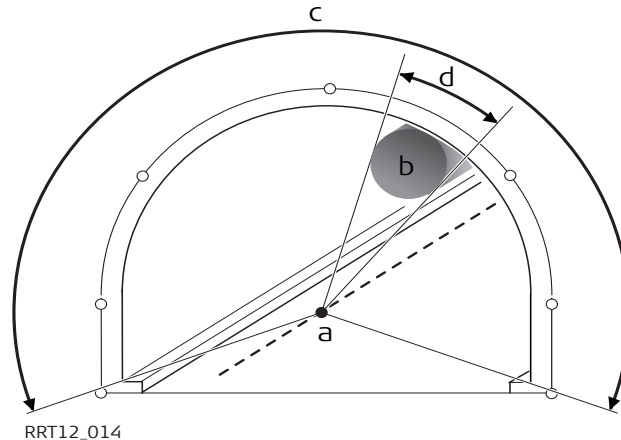
Once the chainages of the profiles to scan have been defined, and before starting the measurement, it is necessary to define the limits of the scan. The scan limits are used to define the angular limits to be scanned in a plane perpendicular to the centreline. These limits normally define the starting point and end point of the profile to scan as well as any zone that should not be measured.



The scan limits can be defined using the **LIMIT (SHIFT-(F5))** key in the **Scan Profile** dialogue.

Limits are defined with respect to the instrument axis. In the following example a limit is defined that includes the entire area to be scanned (Limit 1) and an overlapping area (Limit 2) that should not be scanned because a ventilation shaft is obstructing a clear view of the tunnel surface.

Any number of limits may be defined. In addition each limit needs to be defined as an include limit (ie. measure within the defined zone) or an exclude limit (ie. do not measure within the defined zone). If overlapping zones are defined, an exclude limit has priority over an include limit.



- a) Instrument axis
- b) Ventilation shaft
- c) Include limit
- d) Exclude limit



New limits can be defined by pressing the **NEW (F2)** button in the **Angular Limits** dialogue.

To define a limit

17:33	RL	I	STD	Bluetooth	WiFi	Alert	Battery
RR							
New Angular Limits							
Hz	:		379.3453	g			
V	:		98.7782	g			
Slope Dist	:		40.116	m			
Limit Name	:		3				
Angle Start	:		98.0880	g			
Angle End	:		98.7782	g			
Meas. Status	:		No	↔			
Increment	:		0.500	m			
				A	↑		
CONT	DIST		POSIT				

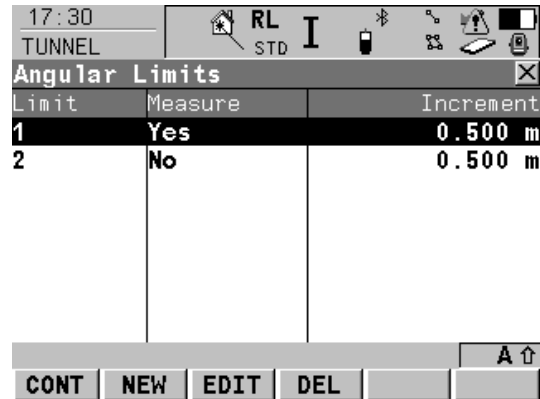
1. Enter the **Limit Name** and place the cursor on the **Angle Start** line.
2. Turn the instrument to point at the starting angle of the limit.
3. Press the **DIST (F2)** key to measure the distance.
4. Move the cursor to the **Angle End** line.
5. Turn the instrument to point at the end angle of the limit.
6. Press the **DIST (F2)** key to measure the distance.
7. Decide on whether the limit is an include limit within which points should be measured (**Meas.Status = Yes**) or an exclude limit which should not be measured (**Meas.Status = No**)
8. If the measurement status is set to **Yes**, enter the approximate distance between points to be measured on the line Increment.



The position of the limit can be reviewed once it has been defined by placing the cursor on the **Angle Start** or **Angle End** line and pressing the **POSIT (F4)** key. The instrument will turn to the corresponding angle.

Store a limit

Once the limit has been defined, it can be stored using the **CONT (F1)** key. The application will then return to the **Angular Limits** dialogue.



Once the limits have been defined they may be edited from the **Angular Limits** dialogue by pressing the **EDIT (F3)** key or deleted by pressing the **DEL (F4)** key.

To return to the **Scan Profile** dialogue after defining the angular limits, press the **CONT (F1)** key.

3.3.3

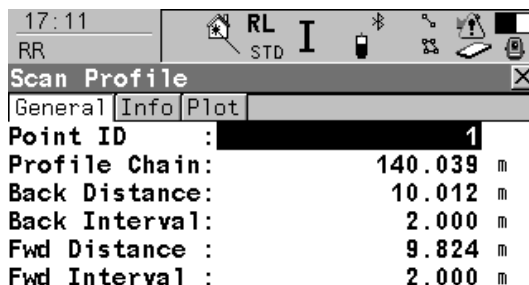
Defining Discrete Points to Measure

Measure additional points

In addition to defining the chainage and the angular limits of the profiles to scan, it is also possible to define discrete points in the profile that should be measured at each chainage.

These points could represent a breakpoint in the section, for example, or a point that is required for positioning services such as electricity cables.

To define a manual point:



1. Press the **MANU (F4)** button in the **Scan Profile** dialogue.
2. Aim at the point to measure.
3. Use the **ALL (F1)**, **DIST (F2)** and **REC (F3)** keys to measure the point in the usual manner.
4. Repeat the process for all of the manual points that are required to be added to the profile.



3.3.4

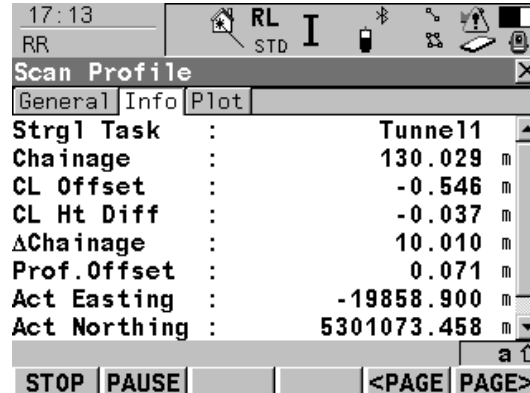
Making a Scan

Starting the scan

Once all manual points have been defined, the scanning of the profiles may commence by pressing the **AUTO (F4)**. If no manual points are required, scanning of the profiles may be started by pressing the **START (F1)** key.

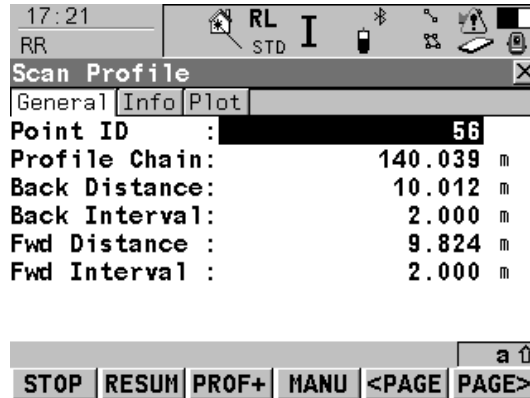
Once scanning has started, the values of the measured point may be viewed in the Info panel of the **Scan Profile** dialogue. The values shown in this panel may be configured in the application configuration. Refer to chapter "7 Configuration" for more information on modifying the Info panel.

It is possible to abort the scan once started using the **STOP (F1)** key. Should it be necessary to pause the scan, for example to allow passing site traffic through, this can be done using the **PAUSE (F2)** key.



Pause and options before continuing

Once the scan has been paused, the user has several options available before continuing:



STOP (F1)

Aborts the scan

RESUM (F2)

Continue the scan at the next position.

Turn the instrument to skip a section of the profile if needed.

PROF+ (F3)

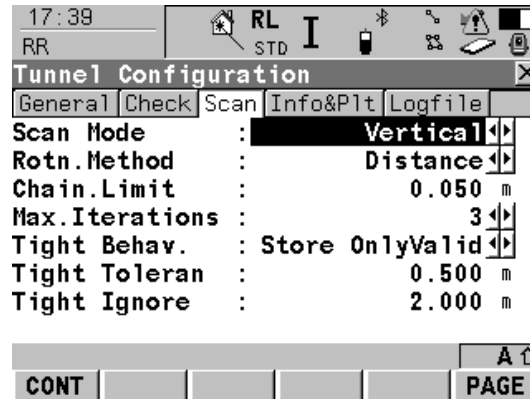
Skips the remaining points in the profile being measured and moves onto the next profile.

MANU (F4)

Allows a point measured manually to be added to the measured profile. The automatic scan may be resumed by pressing the **AUTO (F4)** key if this key has been pressed.

Scan settings

Whilst scanning, the application makes a series of checks based on the values entered in Scan page of the application configuration. These checks ensure that the measurements are within the required tolerance values.



CONF (SHIFT-(F2))

To open the Scan page of the configuration within the application.

Scan Mode

The **Scan Mode** indicates the type of profile to be scanned. Vertical and perpendicular (tilted) profiles are supported.

Rotn.Method

The **Rotn.Method** defines how the distance between points is defined. At the present time, the only available method is by distance.

Chain.Limit

The **Chain.Limit** defines the maximum difference in chainage with which a point will be recorded. It is also related to the **Max.Iterations** parameter. When measuring parallel profiles it is necessary to check the measured chainage of a point against the nominal chainage. Since no information is available regarding the tunnel surface before scanning, the theoretical position of the point is measured.

If the difference between the measured values and the nominal values are greater than the chainage limit, the instrument iterates to a new position where its calculated point is likely to be.

Invalid measurements

This process is repeated until the measured point is within the chainage limit or the maximum number of iterations has been reached. Should this happen, the user is advised that it has been unable to measure the point. This situation could occur, for example, in irregular tunnel surfaces, where the horizontal alignment is formed by a curve with a small radius or if the back distance or forward distance defined in the **General** page of the **Scan Profile** dialogue were too large.

Tolerance values

The tight behaviour (**Tight Behav.**), tolerance (**Tight Toleran**) and **Tight Ignore** refer to the distance of the measured point from the design profile. If the distance between the measured point and the design profile is greater than the tight tolerance and less than the tight ignore value, the application will perform the action defined as the tight behaviour. This may be Store all the values, Store only those values within the defiend tolerances, Pause the application with a warning message and store the values or pause the application with a warning message.



It is possible to return to the **Scan Profile** dialogue from the configuration by pressing the **CONT (F1)** key.

4

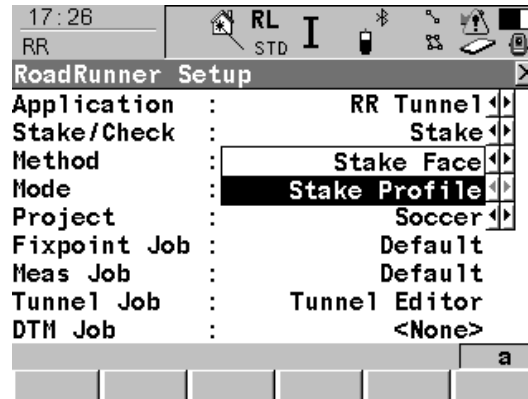
Setting Out the Tunnel

4.1

Overview

Stake Face and Profile

The Stake Face and Stake Profile options can be accessed from the RoadRunner Setup Panel.



CONT (F1)

Select the required option and press the
CONT (F1) key to proceed.

The **Stake Face** option allows any point on the excavation face of the tunnel to be set out. The points to set out may be defined with respect to the horizontal and vertical alignment or to the design profile.

The **Stake Profile** option allows any point at a given chainage in the tunnel to be staked. The points to set out may be defined with respect to the horizontal and vertical alignment or to the design profile.

4.2

Setting Out the Tunnel Face

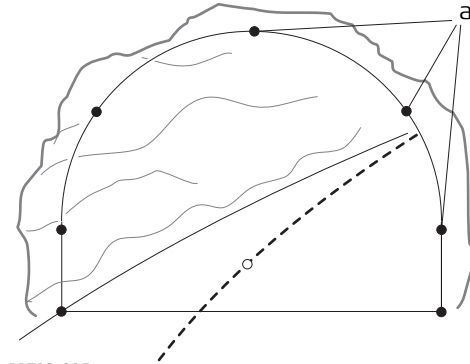
Overview

When excavating a tunnel, it is usually required to set out the tunnel portal before excavation can begin. In addition, for excavation methods other than those involving tunnel boring machines (TBM's), it is then usually required to set out the tunnel face at given intervals during the excavation.

The tunnel face can be set out at any time within the System 1200 RoadRunner Tunnel application using the **Stake Face** function.

This function allows the setting out of a series of points perpendicular to the horizontal alignment that indicate the position of the design profile at the chainage of the tunnel face.

Cross-Section View



RRT12_015

a Points to set out

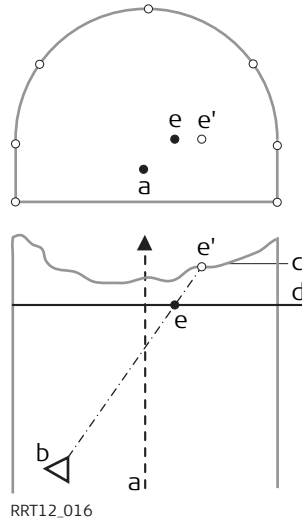
Given that it is likely that a degree of rock debris is present at the tunnel face or that inexact excavation techniques such as blasting are used, it cannot be assumed that the tunnel face at any stage of the excavation is perpendicular to the horizontal alignment.

This in turn implies that we cannot set out a point on the tunnel face at a given chainage as the chainage of the tunnel face at any particular point is unknown. Iterative techniques are necessary to enable any defined point on the tunnel face to be set out accurately.

The **Stake Face** function involves setting out a point on the tunnel face at this unknown chainage. First of all the point to set out on the tunnel face is set out at an approximate chainage (e).

The point may be defined by offsets with respect to the centre line or by its position along the design profile and its offset from the profile. Given that the excavated tunnel face does not intersect the defined chainage, another point (e') is measured.

1st iteration

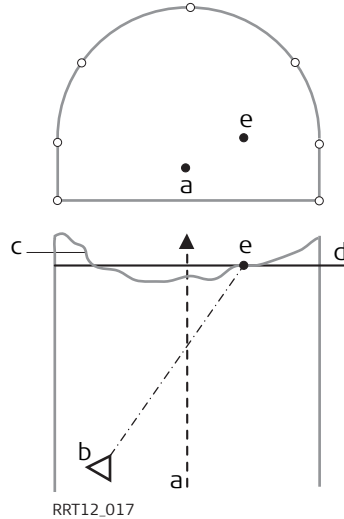


- a) Centre line
- b) Instrument position
- c) Tunnel face
- d) Approximate chainage to set out
- e) Point to set out at approximate chainage
- e' Point set out on tunnel face

The true chainage of the measured point of the first iteration (e') is then calculated and the defined point (e) is set out at the calculated chainage (d).

2nd iteration

This process is repeated until the differences between set out point and the defined point are within a tolerance set by the user.



- a) Centre line
- b) Instrument position
- c) Tunnel face
- d) Calculated chainage from 1st iteration
- e) Point to set out at calculated chainage

4.2.1

Creating a Task

Task definition

Before staking the tunnel face, a task needs to be created to define the shifts to be used during setting out.

Name	Date
REF2_25	06.03.06
REF2_23	06.03.06

CONT (F1)

Selects the highlighted task and proceeds to the **Stake Begin** panel.

NEW (F2)

Starts the task wizard.

TEMP (F6)

Creates a temporary task.



More information on shifts can be found in chapter "1.4 Shifts".

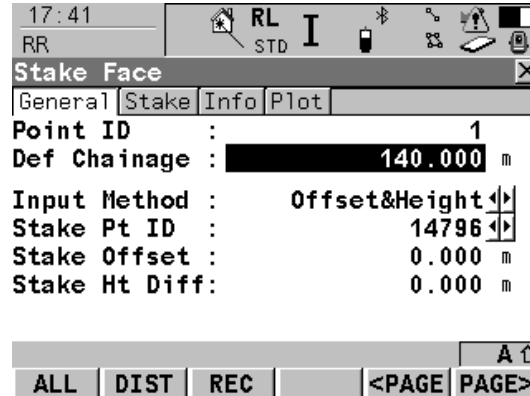
More information on creating tasks can be found in chapter "6.3 Tasks".

4.2.2

Setting Out the Point

General Panel

The approximate chainage of the point to stake and the offsets from the centre line can be defined in the **General** panel of the **Stake Face** dialogue.

**Point ID**

The point identifier of the point that will be set out.

def Chainage

The defined or approximate chainage of the point to be set out.

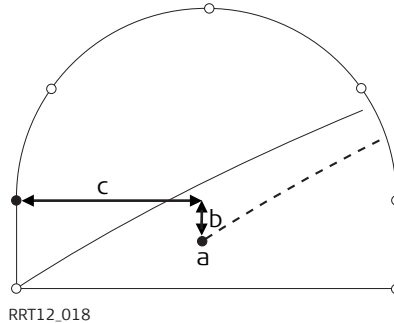
Input Method

Three methods are available to define the position of the point to be set out:

- Offset & Height
- ProfDist & Offset
- Element & Offset

Offset & Height

- **Offset&Height:** The point is set out with a known perpendicular and vertical offset from the horizontal and vertical alignments respectively.
- If the **Offset&Height** method is used, the offsets of the point may be stored as coordinates in the fixpoint job.
- The **Stake Offset** may be stored as the X coordinate and the **Stake Height Difference** may be stored as the Y coordinate.
- To select a point stored in the fixpoint job, place the cursor on the **Stake Pt ID** and press the **ENTER** key.



- a) Centre line
- b) Centre line height difference
- c) Centre line Offset

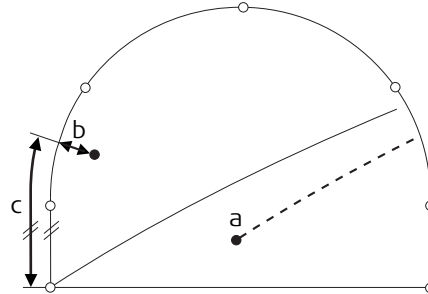


For more information on working with points in the fixpoint job, refer to the TPS User manual.

ProfDist&Offset

The point is defined by the distance from the start of the profile and an offset perpendicular to the design profile.

If this option is used, enter the distance **Along Profile** and the **Profile Offset** to define the point to be set out.



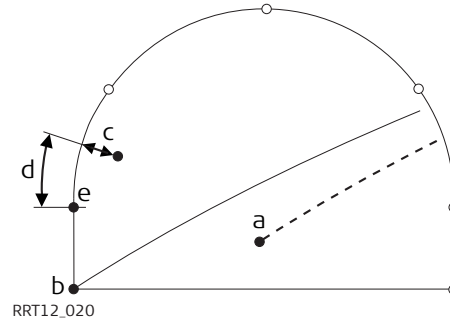
RRT12_019

- a) Centre line
- b) Profile offset
- c) Distance from start of design profile

Element&Offset

The point to set out is defined by the number of the element on which the point lies, the percentage of the distance along the element of the point to set out and the offset perpendicular to the design profile.

Element number 1 is the first element of the design profile. If the configuration parameter **Geometry** is set to **Clockwise** the number of each element increments in a clockwise direction. If this parameter is set to **CounterClockwise** the number of each element increments in a counter-clockwise direction.



- a) Centre line
- b) Point defining start of design profile
- c) Offset perpendicular to profile segment
- d) Distance from start of Start point of segment
- e) Start point of segment



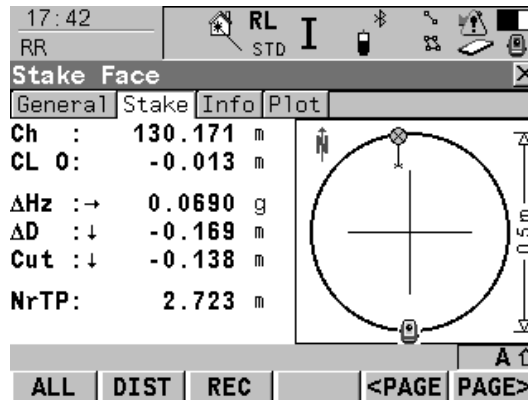
Once the point to set out has been defined, the sensor may be positioned manually and the **ALL (F1)**, **DIST (F2)** and **REC (F3)** keys may be used to measure a point manually.

Auto positioning

The **POSIT (SHIFT-(F5))** key may be pressed to stake the point automatically and start the iterative setting out process. The sensor will set out the point according to the process described in chapter "4.2 Setting Out the Tunnel Face" until:

- the number of iterations set as the configuration parameter **Max Iteration** is reached, or
- the difference between the measured point and the design point is less than the value set as the configuration parameter **Position Tol**.

Stake Face Panel



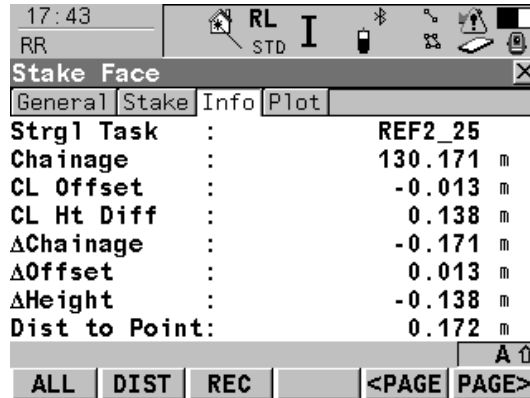
During stake out the differences between the measured point and the design point may be seen in the **Stake Face** panel.

The layout of this panel may appear with or without graphics depending upon the values set in the application configuration.



Refer chapter "7 Configuration" for more information on the configuration.

Info Panel



The Info panel may be configured in the application configuration to display a series of values related to the setting out of the design point as required by the user.



Refer to chapter "7 Configuration" for more information on configuring the Info page.

4.3

Setting Out a Tunnel Profile

Overview

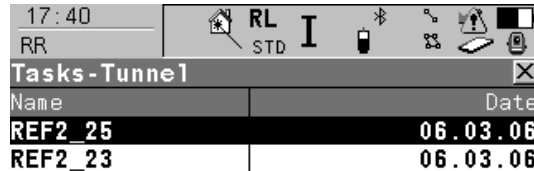
The **Stake Profile** option allows any point at a given chainage in the tunnel to be set out. The points to set out may be defined with respect to the horizontal and vertical alignment or to the design profile.

4.3.1

Creating a Task

Starting with task definition

Before staking the tunnel profile, a task needs to be created to define the shifts to be used during setting out.



Name	Date
REF2_25	06.03.06
REF2_23	06.03.06

CONT (F1)

Selects the highlighted task and proceeds to the **Stake Begin** panel.

NEW (F2)

Starts the task wizard.

TEMP (F6)

Creates a temporary task.



More information on shifts can be found in chapter "1.4 Shifts"

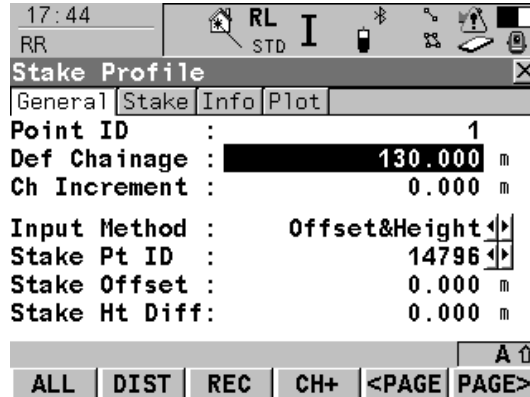
More information on creating tasks can be found in chapter "6.3 Tasks".

4.3.2

Setting Out the Point

General panel

The chainage of the point to stake and the offsets from the centre line can be defined in the **General** panel of the **Stake Profile** dialogue.

**Point ID**

The point identifier of the point that will be set out.

def Chainage

The defined or approximate chainage of the point to be set out.

Ch.Increment

If a point is to be staked at more than one chainage, a chainage increment may be defined. Once a point is set out at the current defined chainage and the **CH+1 (F4)** key is pressed, the defined chainage will be incremented by the chainage increment value to define a new point to set out with the same offsets at the incremented chainage.

Input Method

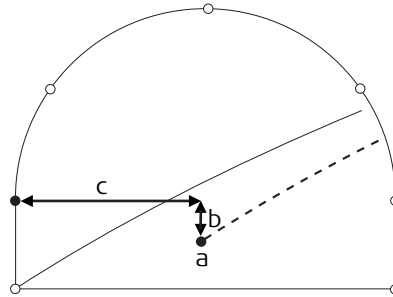
Three methods are available to define the position of the point to be set out:

Offset&Height

The point is set out with a known perpendicular and vertical offset from the horizontal and vertical alignments respectively.

If the **Offset&Height** method is used, the offsets of the point may be stored as coordinates in the fixpoint job. The **Stake Offset** may be stored as the X coordinate and the **Stake Height Difference** may be stored as the Y coordinate.

To select a point stored in the fixpoint job, place the cursor on the **Stake Pt ID** and press the **ENTER** key. For more information on working with points in the fixpoint job, refer to the TPS1200 User manual.



RRT12_018

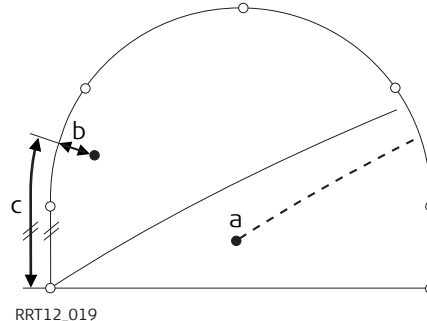
- a) Centre line
- b) Centre line height difference
- c) Centre line offset



The chainage entered on the General page is used as horizontal chainage even if the tunnel job has perpendicular profiles.

ProfDist&Offset

The point is defined by the distance from the start of the profile and an offset perpendicular to the design profile. If this option is used, enter the distance **Along Profile** and the **Profile Offset** to define the point to be set out.



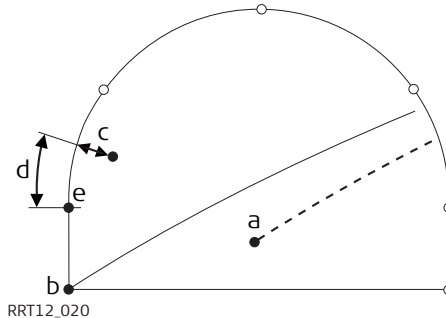
- a) Centre line
- b) Profile offset
- c) Distance from start of design profile



If the tunnel job has perpendicular profiles the chainage entered on the General page is used as vertical chainage.

Element&Offset

The point to set out is defined by the number of the element on which the point lies, the percentage of the distance along the element of the point to set out and the offset perpendicular to the design profile. Element number 1 is the first element of the design profile. If the configuration parameter **Geometry** is set to **Clockwise** the number of each element increments in a clockwise direction. If this parameter is set to **CounterClockwise** the number of each element increments in a counter-clockwise direction.



- a) Centre line
- b) Point defining start of design profile
- c) Offset perpendicular to profile segment
- d) Distance from start of Start point of segment
- e) Start point of segment



If the tunnel job has perpendicular profiles the chainage entered on the General page is used as vertical chainage.



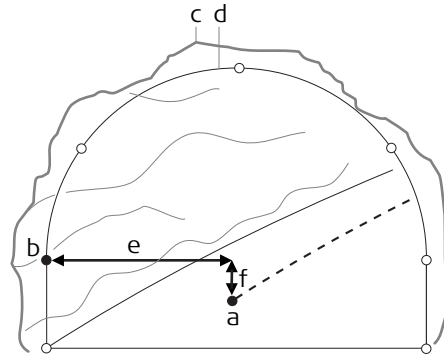
Once the point to set out has been defined, the sensor may be positioned manually and the **ALL (F1)**, **DIST (F2)** and **REC (F3)** keys may be used to measure a point manually.

Auto positioning

The **POSIT (SHIFT-(F5))** key may be pressed to stake the point automatically. The sensor will aim towards the point at the given chainage and offsets and measure a distance. If this distance is not within the required tolerance an iterative process is started until:

- the number of iterations set as the configuration parameter **Max Iteration** is reached, or
- the difference between the measured point and the design point is less than the value set as the configuration parameter **Position Tol.**

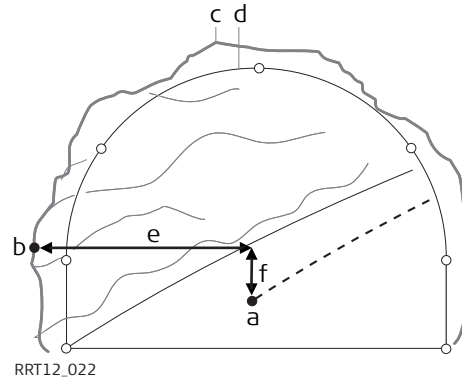
Stake point on surface



RRT12_021

- a) Centre line
- b) Design point to set out
- c) Excavated profile
- d) Design profile
- e) Centre line offset
- f) Centre line height difference

If it is not possible to set out the defined point, as seen in the diagram, between successive iterations, the sensor will maintain the chainage and height difference from the vertical alignment fixed and modify the horizontal offset from the centre line to calculate the new position of the point. The point that will be set out will thus maintain the defined chainage and height difference but will have a modified offset value from the centreline.

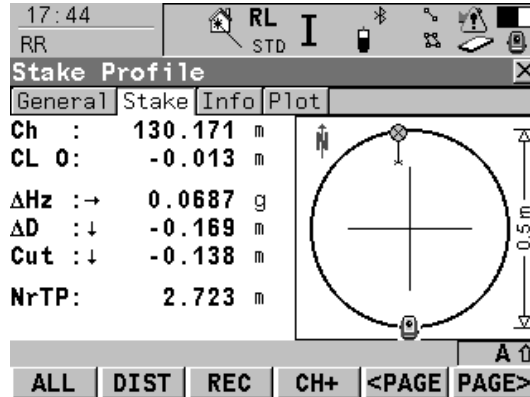


- a) Centre line
- b) Design point to set out
- c) Excavated profile
- d) Design profile
- e) Centre line offset
- f) Centre line height difference

Stake Profile panel

During stake out the differences between the measured point and the design point may be seen in the **Stake Profile** panel.

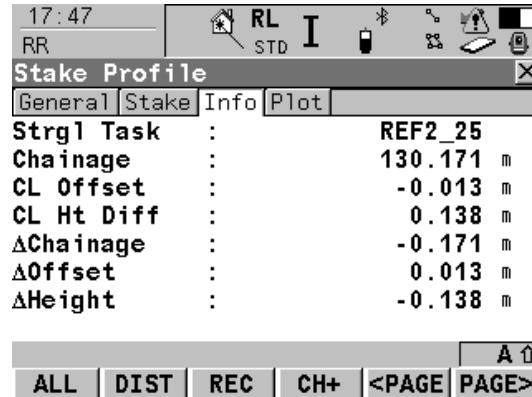
The layout of this panel may appear with or without graphics depending upon the values set in the application configuration.



Refer to chapter "7 Configuration" for more information on the configuration.

Info panel

The **Info** panel may be configured in the application configuration to display a series of values related to the setting out of the design point as required by the user.



Refer to chapter "7 Configuration" for more information on configuring the Info page.

5

Project and Job Management

5.1

Overview

Project data

Working on a tunnel construction site implies working with various data such as:

- Control points
- Horizontal and vertical alignments
- Measurement data
- Tunnel Profile design
- Digital Terrain Models

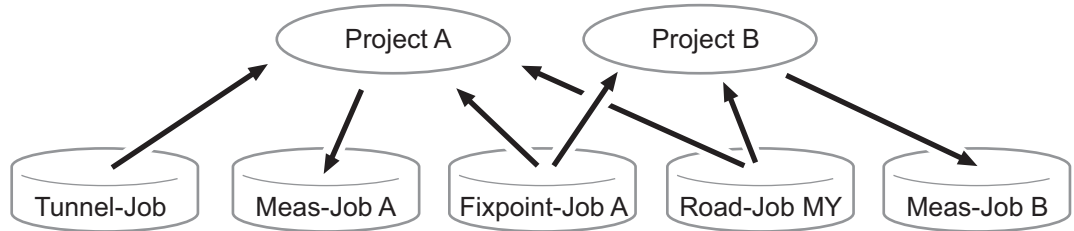
To avoid having to select individual data sets each time the application is used, data can be grouped into projects. This makes the selection much easier and reduces the risk of selecting wrong data set.

Project

A project consists of different kinds of jobs that are grouped together to form a project. By selecting a project automatically all referenced jobs are selected as well. A project can reference:

- one fixpoint job
- one measurement job
- one road job
- one tunnel job
- one DTM job.

Since jobs are only referenced by a project, they may be used in more than one RoadRunner project, as well as in other applications. For example the same collection of control points may be used in two different projects.



RRT12_027

Project A and Project B reference the same fixpoint job (**Fixpoint Job A**) and road job (**Road-Job MY**), however, their results are stored into different measurement jobs (**Meas-Job A**; **Meas-Job B**). In addition, Project A references the tunnel design data through a Tunnel Job (**Tunnel Job A**).

- Fixpoint job** The Fixpoint job holds all control point information needed in the field. For example, control points, points with known coordinates used for a TPS set-up.
- Measurement Job** The measurement job is where information generated in the field is recorded. All measurements, points and other values stored in the field are added to this job.
- Road Job** All road design information for road data outside of the tunnel, either typed in manually or exported from a design package is stored in the road job. Like the fixpoint job, it is a source of information. Refer to the RoadRunner Technical Reference Manual, chapter "6 Tunnel Job" for more information on road jobs.

Tunnel Job	Contains information relating to the design of the tunnel. The centre line of the tunnel and the tunnel design profiles are stored in the tunnel job. As with a road job, the tunnel job is a read-only source of information. Refer to chapter "6 Tunnel Job" of this manual for more information on tunnel jobs.
DTM Job	Holds DTM or TIN data (Digital Terrain Model; Triangular Irregular Network). Like a fixpoint job or road job, the DTM job is a source of information. Refer to the RoadRunner Technical Reference Manual, chapter 7 "DTM Job" for more information on DTM jobs.

The same job can be used as a data and measurement job.

Road jobs, Tunnel jobs and DTM jobs cannot be selected as a data or a measurement job. When selecting a job, a filter is applied to show only the relevant jobs in the selection list.

5.2

5.2.1

Overview

Selecting a Project

Overview

Upon starting the RoadRunner application, there are two different ways of selecting a project:

- **Select from list:**
Enter a list of projects stored on the CF Card or in the internal memory from the Road-Runner Setup panel.
 - **Resume:**
To resume the last task the project to which the task belongs to is selected automatically.
-

5.2.2

Browse for Existing Project

Browse for project

A list of all available projects in the internal memory or on the CompactFlash card will be opened when pressing **ENTER** on the Projects line of the RoadRunner Setup panel.

Projects (CF Card)	
Name	Date
Soccer	16.10.06
ELLIS	30.10.06
SAMPLE	17.10.06
RR_Exercise_3	31.03.04
RR_EXERCISE_2	31.03.04
RR_Exercise 5	30.03.04
Default Project	30.03.04

Control Bar: CONT NEW EDIT DEL MORE INTL A ↑

CONT (F1)

To select the highlighted project.

NEW (F2)

To create a new project. Refer to "5.3 Creating a New Project".

EDIT (F3)

To edit the highlighted project. This project also becomes the active project. Refer to "5.5 Editing a Project".

DEL (F4)

To delete the highlighted project. Refer to "5.4 Deleting a Project".

MORE (F5)

To toggle between Date and Time info.

CFCRD (F6) or INTL (F6)

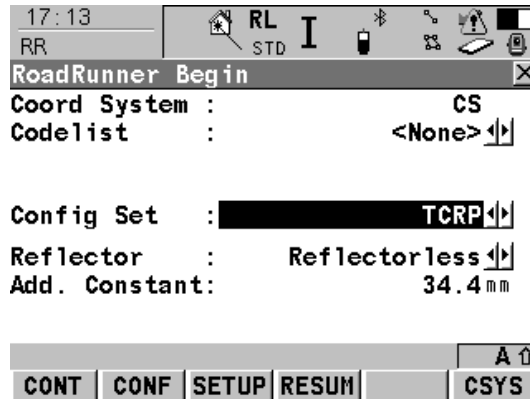
To switch between the CompactFlash card and internal memory as the active device.

5.2.3

Resuming the Last Task

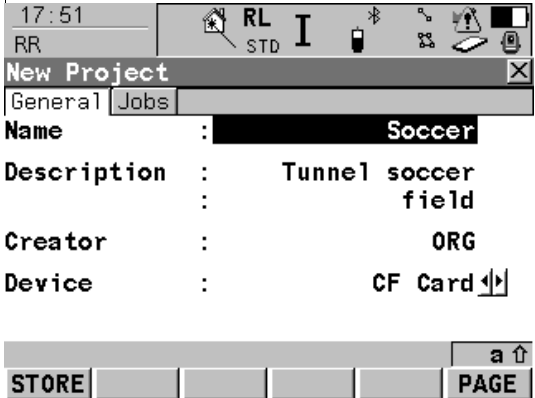
Resume task

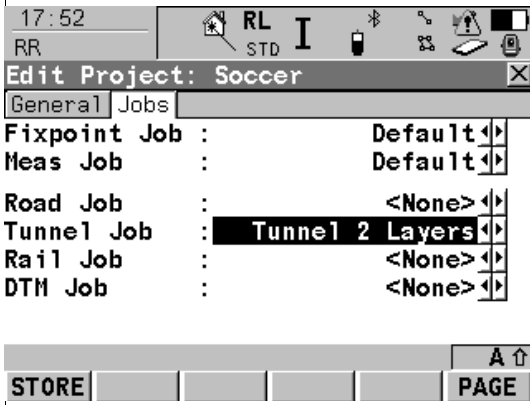
RoadRunner retains the last active task used on any project. When the application is resumed, the last active task may be accessed again using the **RESUM (F4)** key. This avoids the selection of project, method and task to be staked out or checked every time the application is started.



5.3 Creating a New Project

Create a project step-by-step

Step	Description
1.	 <p>17:51 RR</p> <p>New Project</p> <p>General Jobs</p> <p>Name : Soccer</p> <p>Description : Tunnel soccer field</p> <p>Creator : ORG</p> <p>Device : CF Card</p> <p>STORE PAGE a ↑</p> <p>Define the <Name:>, <Description:>, <Creator:> and <Device:> for the project. The <Name:> is mandatory.</p>
2.	PAGE (F6) changes to the Jobs page.

Step	Description
3.	 <p>Select the <Fixpoint Job:>, <Meas Job:>, <Road Job:>, <Tunnel Job:> and <DTM Job:> to be used in the new project. It is possible to add or remove jobs to the project at a later stage.</p>
4.	<p>STORE (F1) to accept the changes and select the newly created project as the new active project.</p>

5.4

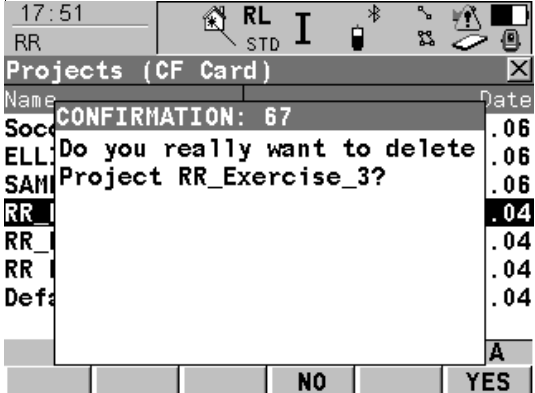
Deleting a Project

General

Deleting a project will not delete the measurement job, fixpoint job, road job, tunnel job and DTM job that it references.

If two projects use the same control points by referencing the same fixpoint job, deleting one project will not delete the control points for the other project.

Deleting project step-by-step

Step	Description
1.	Highlight the project to delete in the Projects panel.
2.	<p>DEL (F4) to delete the project.</p> 
3.	<p>YES (F6) to confirm deletion, NO (F4) to return to the previous screen.</p>
4.	CONT (F4) to return to the RoadRunner Start panel.

5.5 Editing a Project

General page

The project details contain general information about the project as well as the list of jobs referenced by the project. Project details may be edited using the EDIT (**F4**) key in the Projects panel.

The screenshot shows a handheld device screen with a status bar at the top displaying '17:52' and 'RR'. Below the status bar is a navigation bar with icons for home, RL, STD, and I. The main screen title is 'Edit Project: Soccer'. Below the title is a tabbed interface with 'General' and 'Jobs' tabs. The 'General' tab is active, showing the following fields:

- Name** : Soccer
- Description** : Tunnel soccer field
- Creator** : ORG
- Device** : CF Card

At the bottom of the screen, there is a row of buttons: 'STORE', 'PAGE', and 'A ↑'.

CONT (F1)

To accept changes and return to the screen from where this screen was accessed.

PAGE (F6)

changes to the Jobs page. All jobs referenced by the project are listed.

<Name:>

Project name, must be unique. This field is mandatory.

<Description:>

User input. Two line description of the project.

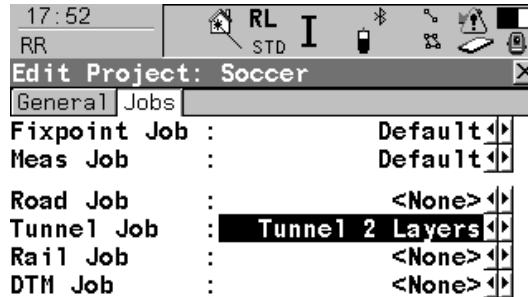
<Creator:>

User input. Name of the creator of the project.

<Device:>

CompactFlash Card or Internal Memory. The device on which the job is stored.

Job page



STORE (F1)

To accept the changes and return to the screen from where this screen was accessed.



<Fixpoint Job:>

The job that contains the point data to be used.

<Meas Job:>

The active job which also determines the coordinate system.

Points which are recorded during staking out or check are stored in this job.

<Road Job:>

The active road job.

<Tunnel Job:>

The active tunnel job.

<DTM Job:>

The active DTM job.

6

Tunnel Job

6.1

Overview

General

Each tunnel job consists of two major parts:

- **Design data:** Contains all the information about the tunnel design including the geometry of the centre line and the tunnel cross-section.
 - **Working tasks:** Tasks define how the design elements of the tunnel are staked out or checked in the field, they also define any offsets that should be applied to the design data. Refer to "6.3 Tasks" for more information on tasks.
-

6.2

6.2.1

Alignments

Design Data

Horizontal and Vertical Alignments

All tunnel jobs must consist of at least a horizontal and a vertical alignment. These data may be converted from a road design package using the Design To Field component within the Leica Geo Office application.

6.2.2**Design Profiles****Profiles**

Depending on the complexity of the tunnel job, the design data may vary from being a single horizontal and vertical alignment to a design containing many different design profiles with dozens of defined vertices.

Design profiles may be defined and edited in the Profile Editor application that is integrated into the LEICA Geo Office (LGO) application.

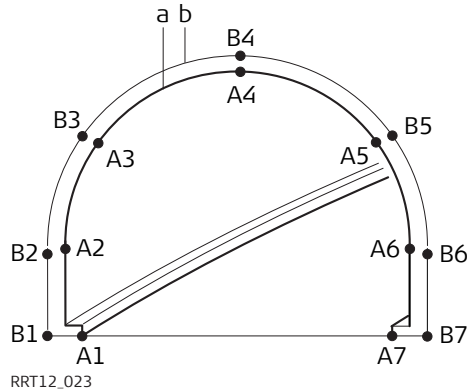
6.2.3

Layers

Layers

Tunnels generally consist of layers made of different materials, for example a shotcrete surface or a lining. At different times throughout a project it may be required to work with different layers of the tunnel.

RoadRunner allows the possibility of creating such layers by grouping together design profiles that will be used at the same chainage.



- a) The vertices **A1-A7** could be grouped together in a layer (**a**) and represent the final lining of the tunnel.
- b) The vertices **B1-B7** could be grouped together in a layer (**b**) and represent the inner shotcrete layer of the tunnel.

Design Profile Layers may be assigned to chainages along the centre line using the Profile Editor within LGO.

The layer of the tunnel to set out or check may be defined when creating a task.

6.3

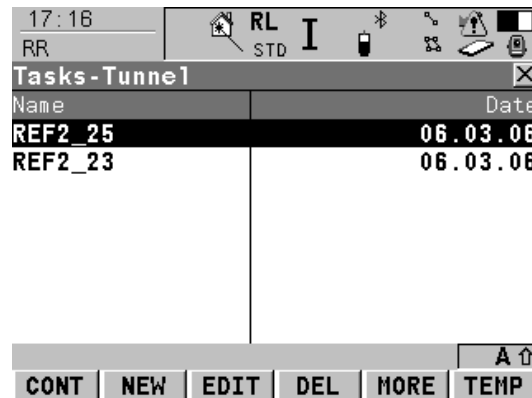
Tasks

Overview

When staking out or checking a tunnel, it is often the case that it is not possible to finish a particular task in one go. RoadRunner Tunnel allows the possibility of storing the element to be staked out or checked together with all defined settings as a work task. Tasks are stored as a part of the project.

A task defines the offsets required for setting out and checking as well as the layer of the design profile to use and the chainage limits within which the task applies.

When pressing **CONT (F1)** on the RoadRunner Setup panel a list of available tasks will be shown.

**CONT (F1)**

Select the highlighted task and continue.

NEW (F2)

Create a new task.

EDIT (F3)

Modify selected task.

DEL (F4)

Delete selected task.

MORE (F5)

Toggle between Date and Time info.

TEMP (F6)

Create a new temporary task. The task is created in the same way as an ordinary task but the task is not saved.

6.3.1

Creating a New Task

Overview

The Selection Wizard-Start page defines the name of the task and whether shifts should be applied to the design data.

Shifts are applied temporarily to the design data for the defined task, the original design data is not modified when a shift is applied.



Refer to chapter "6.3.2 Working with Shifts" for more information on applying shifts.

Creating a task step-by-step

The same selection wizard is used for all tasks within the application.

17:53 RR RL STD I [Bluetooth] [Wi-Fi] [Mobile Data] [Battery] [Signal]

Selection Wizard-Start [X]

Task Type : Tunnel

Task Name : SHOTCRETE

Shift Horizontl: None

Shift Vertical: None

Shift X-Sec : None

NEXT [] [] [] [] [A ↑]

NEXT (F1)

Move on to the next page of the selection wizard.

The second page of the selection wizard defines the layer of the design profile to be used for the task.

**NEXT (F1)**

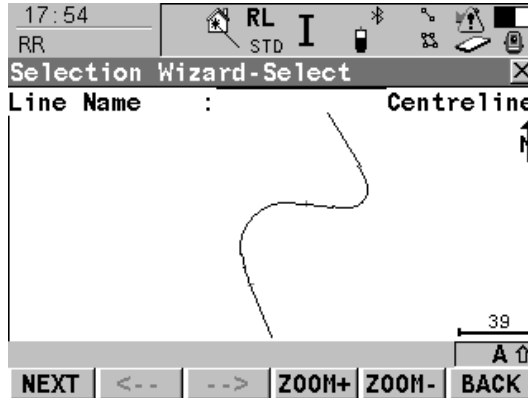
Move on to the next page of the selection wizard.

BACK (F6)

Go back to the previous page of the selection wizard.



The next page of the wizard displays the horizontal alignment. Given that this is the only stringline available in a tunnel job, this page is purely informative.



NEXT (F1)

Move on to the next page of the selection wizard.

BACK (F6)

Go back to the previous page of the selection wizard.

This page of the selection wizard defines whether the task should only be applied to a limited section of the alignment. If the defined chainage range is exceeded during stake out/check a warning appears.

17:55
RR

RL
STD I

Selection Wizard-Define

Centre line : Centreline

Use Min/Max : Yes

Min Chainage : 100.000 m

Max Chainage : 285.746 m

FINSH DEFLT BACK

A ↑

FINSH (F1)

Finish the selection wizard and return to the task selection page.

DEFLT (F5)

Set the chainage limits to the maximum and minimum chainage available in the tunnel job.

BACK (F6)

Go back to the previous page of the selection wizard.

6.3.2

Working with Shifts

Overview

If a shift is defined on the first page of the selection wizard, the parameters associated with the shift must be entered after defining the chainage limits.

Two types of shifts may be applied:

- Constant or
- linear.

The application of the shift is dependent upon to which entity it should be applied:

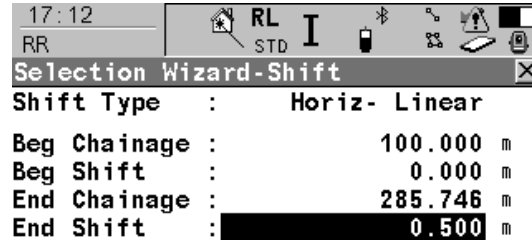
- Horizontal alignment,
- Vertical alignment or
- Design Profile.



Refer to chapter "1.4 Shifts" for more information on the type of shift for each entity.

For linear shifts

The parameters required for applying the shift are identical for all entities.

**Beg Chainage**

Chainage from which the shift should be applied.

Beg Shift

Magnitude of the shift to apply at the begin chainage.

End Chainage

Chainage at which the shift should end.

End Shift

Magnitude of the shift to apply at the end chainage.

For constant shifts



17:12
RR

RL STD I

Selection Wizard-Shift

Shift Type : Vert- Constant

Beg Chainage : 100.000 m

Beg Shift : 0.100 m

End Chainage : 285.746 m



FINSH [] [] [] BACK

A ↑

Beg Chainage

Chainage from which the shift should be applied.

Beg Shift

Magnitude of the shift to apply.

End Chainage

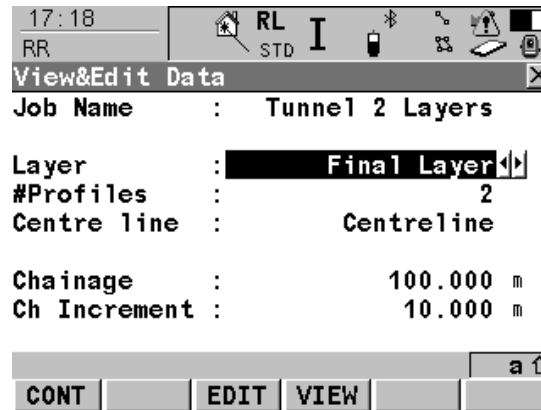
Chainage at which the shift should end.

6.4 Viewing and Editing the Design Data

6.4.1 Overview

Viewing and Editing

The design data stored within the tunnel job contains all of the information about the tunnel design. This includes the stringlines and layers (for example, the geometry of the centre line or the layers of the different materials/surfaces which form the tunnel). The design data can be viewed and partially edited in these View and Edit screens.



CONT (F1)

To return to the RoadRunner Tunnel Setup screen.

EDIT (F3)


To edit the following design data:

- 1) to edit the general job details,
- 2) to change the start chainage of the centre line of the selected layer.

VIEW (F4)

To view the following design data in a selected layer:

- 1) to view specific details of the layer centre line,
- 2) to view cross-section plots.

Field	Description of field
Job Name	The name of the active tunnel job, as defined in the project.
Layer	To select a layer from the active tunnel job. All of the layers within the active tunnel job can be selected.
#Profiles	The number of profiles from the selected layer.
Centre line	The name of the layer centre line.
Chainage	To enter a start chainage to use when viewing the data. The default value is the start chainage of the layer centre line.
Ch Increment	To enter a chainage increment to use when stepping through the data
	If a centre line has not been defined, a start chainage cannot be entered and the field will be shown as "----". If a centre line has not been defined, a chainage increment cannot be entered and the field will be shown as "-----".

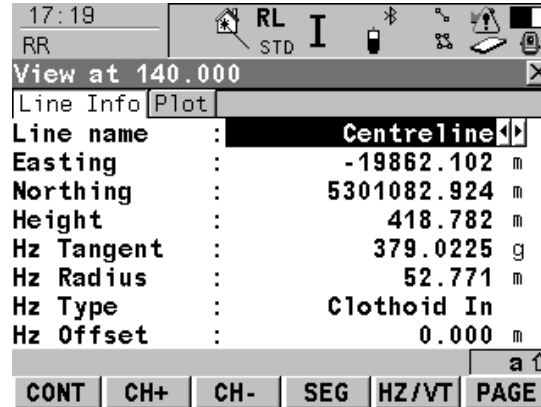
6.4.2

Viewing the Design Data

Viewing details of the layer centre line

This page shows the following:

Geometrical details of the selected stringline at the selected chainage.

**CONT (F1)**

To return to the View&Edit Data screen.

CH+ (F2)

To increase the chainage by the chainage increment, as defined in the View&Edit Data screen.

CH-1 (F3)

To decrease the chainage by the chainage increment, as defined in the View&Edit Data screen.

SEG (F4)

To enter the Segment Info screen.


HZ/VT (F5)

To toggle between the vertical alignment data and the horizontal alignment data.

PAGE (F6)

To move to the next page.

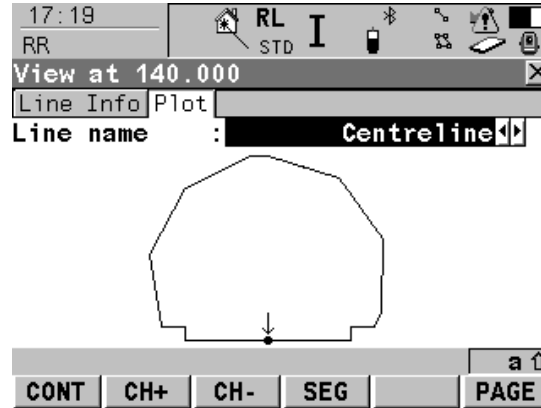
Field	Description of field
Line name	To select a stringline from the layer.
Easting	The East coordinate of the stringline.
Northing	The North coordinate of the stringline..
Height	The height of the stringline.
The following fields/values can be toggled, by using the HZ/VT (F5) softkey:	
Hz Tangent/Grade	The tangent direction or grade of the stringline.

Field	Description of field
Hz/Vt Radius	The horizontal/vertical radius of the stringline segment.
Hz/Vt Type	The horizontal/vertical segment type.
Hz/Vt Offset	The horizontal/vertical offset to the layer centre line.
 If a value has not been defined, the field will be shown as "----".	

Viewing profiles

This page shows the following:

A cross section view of the design data at the selected chainage. No selection or zoom/pan functionality is available.



CONT (F1)

To return to the View&Edit Data screen.

CH+ (F2)

To increase the chainage by the chainage increment, as defined in the View&Edit Data screen.

CH-1 (F3)

To decrease the chainage by the chainage increment, as defined in the View&Edit Data screen.

SEG (F4)

To enter the Segment Info screen.

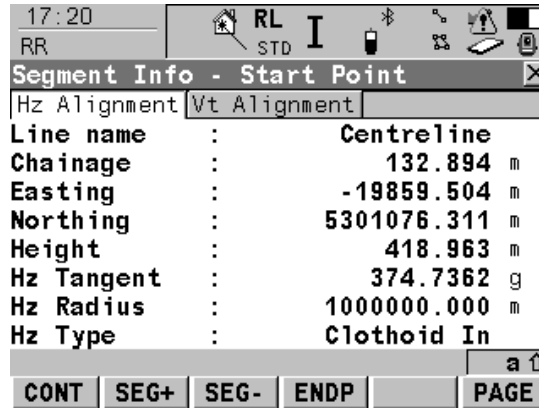
PAGE (F6)

To move to the next page.

**Viewing the segment:
the Hz Alignment page**

This page shows the following:

Detailed horizontal alignment information about the current stringline segment.



CONT (F1)

To return to the View screens.

SEG+ (F2)

To move to the next segment.

SEG- (F3)

To move to the previous segment.


ENDP/STRTP (F4)

To toggle between the start point and the end point of the segment.

PAGE (F6)

To move to the next page.

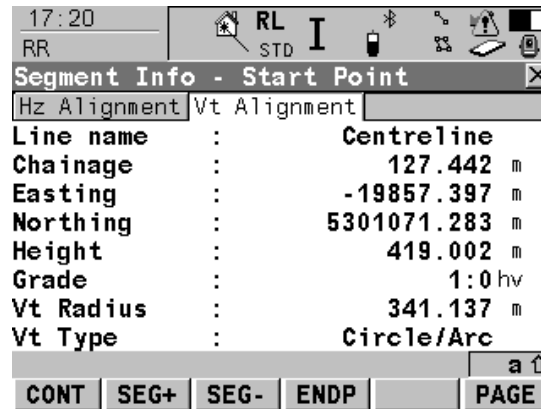
Field	Description of field
Line Name	The name of the selected stringline.
The following fields/values can be toggled, by using the ENDP/STRTP (F4) softkey:	
Chainage	The chainage of start/end point of the segment.
Easting	The East coordinate of the start/end point of the segment.
Northing	The North coordinate of the start/end point of the segment.
Height	The height of the start/end point of the segment.
Hz Tangent	The tangent direction at the start/end point of the segment.
Hz Radius	The radius at the start/end point of the segment (is not toggled).

Field	Description of field
Hz Type	The current segment type (is not toggled).
	If a value has not been defined, the field will be shown as "----".

**Viewing the segment:
the Vz Alignment page**

This page shows the following:

Detailed vertical alignment information about the current stringline segment.



CONT (F1)

To return to the View screens.

SEG+ (F2)

To move to the next segment.

SEG- (F3)

To move to the previous segment.


ENDP/STRTP (F4)

To toggle between the start point and the end point of the segment.

PAGE (F6)

To move to the next page.

Field	Description of field
Line Name	The name of the selected stringline.
The following fields/values can be toggled, by using the ENDP/STRTP (F4) softkey:	
Chainage	The chainage of start/end point of the segment.
Easting	The East coordinate of the start/end point of the segment.
Northing	The North coordinate of the start/end point of the segment.

Field	Description of field
Height	The height of the start/end point of the segment.
Grade	The grade at the start/end poin of the segment (is not toggled).
Vt Radius	The radius at the start/end point of the segment (is not toggled).
Vt Type	The current segment type (is not toggled).
 If a value has not been defined, the field will be shown as "----".	

6.4.3

Editing the Design Data

Editing the job details

17:18
RR
RL STD I
Edit: Tunnel 2 Layers
Job Centreline
Name : Tunnel 2 Layers
Description :
: :
: :
Creator : ~Core Developme
Device : CF Card

STORE PAGE

STORE (F1)

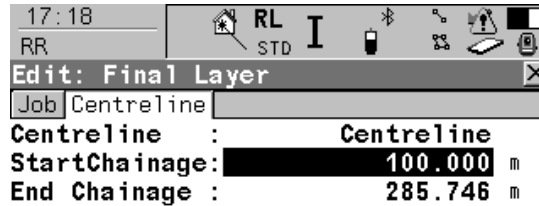
To return to the View&Edit Data screen.

PAGE (F6)

To move to the next page.

Field	Description of field
Name	The unique name of the tunnel job. The name may be up to 16 characters long and may include spaces. This field is mandatory.
Description	A detailed description of the tunnel job (two lines are available). This field is optional.
Creator	The name of the person who created the tunnel job. This field is optional.
Device	CF Card or Internal Memory. The device on which the tunnel job is stored.

Changing the start chainage of the centre line of the selected layer



STORE (F1)

To store data and return to the View&Edit Data screen.

RESET (F4)

To clear all changes made to the start chainage reset to the original start chainage.

PAGE (F6)

To move to the next page.



Field	Description of field
Centreline	The name of the centre line.
StartChainage	To enter a start chainage for the layer centre line. By using the centre line length, the end chainage is automatically calculated.
End Chainage	The end chainage of the layer centre line, as calculated from the start chainage.

7

Configuration

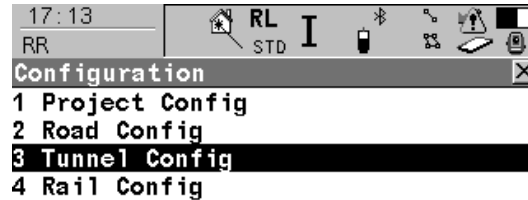
7.1

Three parts of configuration

Overview

The configuration of the RoadRunner application is divided into three parts:

- Project Configuration
- Road Configuration
- Tunnel Configuration
- Rail Configuration



Project and Road Configuration



The values in the **Project Configuration** are general parameters that apply to both Road and Tunnel projects. The values set in the **Road Configuration** apply only to Road projects and the values set in the **Tunnel Configuration** apply only to Tunnel projects.

For more information on the Project and Road Configuration, refer to the RoadRunner Technical Reference Manual.

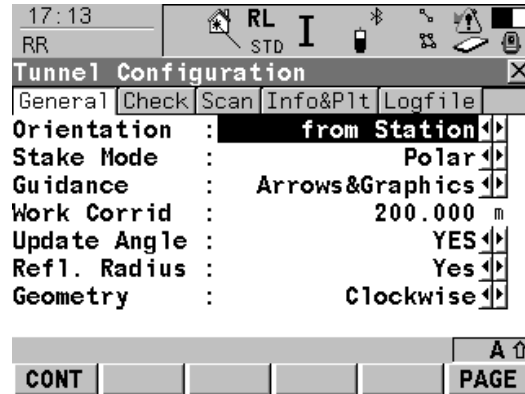
Tunnel Configuration

The Tunnel Configuration consists of five pages where parameters relating to the configuration of the application may be modified. Refer to chapter "7.2 Tunnel Configuration General Page".

7.2 Tunnel Configuration General Page

General Settings

The **General** page allows parameters that will be used throughout the application to be set.



CONT (F1)

To confirm the changes and move to the previous screen.

PAGE (F6)

To go to the next page of the configuration.

Orientation

The reference direction used to stake out points. The stake out elements and the graphics displayed are based on this selection:

To Alignment: The position of the measured point and the calculated differences are displayed relative to the alignment.

To Station: The position of the measured point and the calculated differences are displayed relative to the position of somebody located at the measured point looking towards the sensor.

From Station: The position of the measured point and the calculated differences are displayed relative to the position of somebody located at the sensor looking towards the measured point.

Stake Mode

If the option **To Station** or **From Station** is used, the displayed differences between the measured point and the design point may be configured:

Orthogonal: The differences are displayed as two orthogonal distances left/right and forward/back with respect to the line of sight.

Polar: The differences are displayed as polar coordinates, angle and distance, with respect to the line of sight.

Guidance

Indication of direction and distance from measured point to point to set out:

Off: No graphical guidance is used, only numerical values are available on the screen.

Polar: Forward/Back and Left/Right arrows are shown on the screen.

Graphics: A bulls-eye is shown on the screen.

Arrows&Graphics: Forward/Back and Left/Right arrows and a bulls-eye are shown on the screen.

Work Corridor

Working corridor of tunnel job. If a measured point is further away from the working corridor distance, an error message is displayed.

Update Angle

Update of vertical angle after a distance measurement.

Yes:

The measured point will be projected by a distance equivalent to the radius of the reflector in a direction perpendicular to the tangent of the design profile.

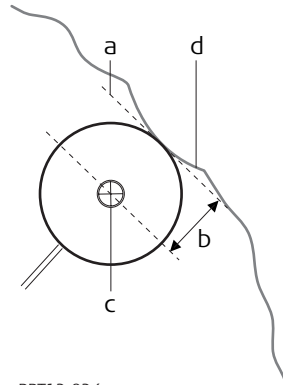
No:

Angles and stake out values are updated only after a distance measurement. All values are then frozen until the next distance is taken.

Refl. Radius

When using a reflector to check a design profile it is important to take into account the reflector radius parameter in the **General** page of the application configuration.

- Yes:** The measured point will be projected by a distance equivalent to the radius of the reflector in a direction perpendicular to the tangent of the design profile.
- No:** The design profile will be compared to the coordinates of the centre of the reflector at the measured position.



RRT12_024

- a) Tangent to design profile
- b) Reflector radius
- c) Reflector
- d) Design profile

If reflectorless measurements are used or no design profile has been defined, the reflector radius parameter will not be used in the calculation.

Geometry

Defines the sense in which the design profile is considered.

Clockwise:

The design profile is defined in a clockwise direction. The number of each element also increments in a clockwise direction.

CounterClockwise:

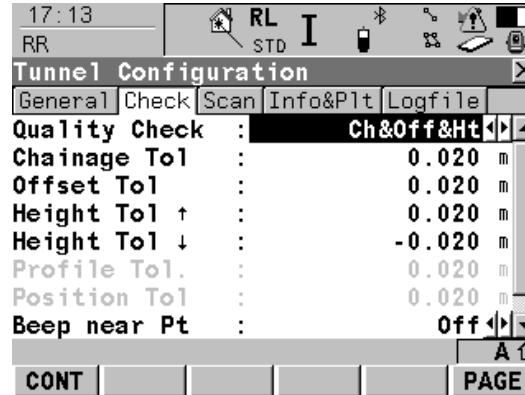
The design profile is defined in a counter-clockwise direction. The number of each element also increments in a counter-clockwise direction.

7.3

Tunnel Configuration Check Page

Check configuration

The **Check** page allows parameters that will be used during Tunnel Check to be set.



CONT (F1)

To confirm the changes and move to the previous screen.

PAGE (F6)

To go to the next page of the configuration.

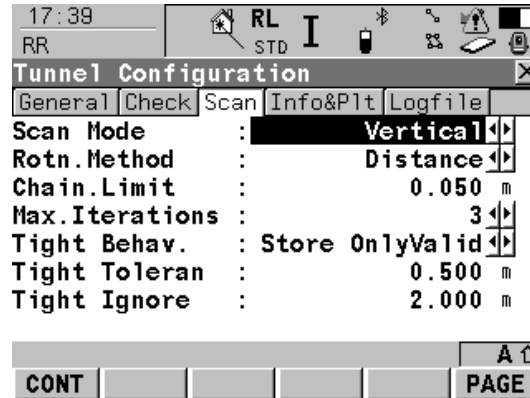
Quality Check	Activates a position check when storing a staked or checked point. When the defined tolerance is exceeded, the stake out/check can be repeated, skipped or stored. Depending on this selection the lines below are enabled/disabled. NONE No quality check during stake out/check of points. Ch&Off&Ht Check for chainage, horizontal offset and height. Ch&Off Check for chainage and horizontal offset. Pos&Ht Check for 2D position and height. Position Check for 2D position. Height Check for height. Profile Check for distance from design profile.
Chainage Tol	From 0.001 to 100 maximum permitted difference in chainage.
Offset Tol	From 0.001 to 100 maximum permitted horizontal offset from defined position.
Height Tol	From 0.001 to 100 maximum permitted height difference.
Profile Tol	From 0.001 to 100 maximum permitted distance from design profile.
Position Tol	From 0.001 to 100 maximum permitted radial horizontal distance.
Beep near Pt	On or Off activates an acoustic warning signal when the horizontal radial distance from the current position to the point to stake out is equal or less than defined in Dist from Pt
Dist from Pt	Available when Beep near Pt: On is selected. Defines the horizontal radial distance from the current position to the point to stake out within which the acoustic warning signal is active.

7.4

Tunnel Configuration Scan Page

Scan configuration

The **Scan** page allows parameters that will be used when scanning profiles to be set.



CONT (F1)

To confirm the changes and move to the previous screen.

PAGE (F6)

To go to the next page of the configuration.

Scan Mode	Indicates the type of profile to be scanned. At the present time the available modes are the measurement of vertical and tilted profiles.
Rotation method	Defines how the distance between points is defined. At the present time, the only available method is By distance .
Chain.Limit	Defines the maximum difference between the measured and defined chainage within which a point will be recorded.
Max.Iterations	The maximum number of attempts that should be made in measuring a point when measuring parallel profiles.
Tight Behav.	Defines the behaviour of the application when a measured point is outside of the defined Tight Tolerance . StoreAll: Store all measurements independent of whether they are within tolerance. Store OnlyValid: Store only the points that are within tolerance. Pause & Store: Store all measurements but if the point is out of tolerance, pause the scan. Pause: Pause the application if a point is out of tolerance.
Tight Toleran	Refers to the maximum permitted distance between the measured point from the design profile. If the distance between the measured point and the design profile is greater than the tight tolerance and less than the tight ignore value, the application will perform the action defined as the tight behaviour
Tight Ignore	If the distance between the measured point and the design profile is greater than the Tight Ignore value, the measurement will be ignored and the values will not be stored.

For more information about Thight Tolerance refer to chapter "1.3.2 Tunnel Profiles".

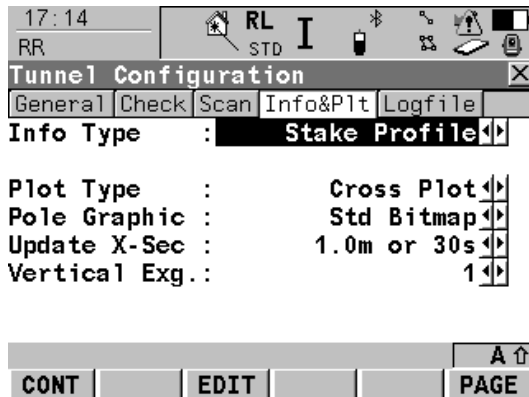


7.5

Tunnel Configuration Info and Plot Page

Overview

The **Info & Plot** page allows the definition of the parameters to be seen on the Info page whilst working with the application. It also allows the parameters to be used for plotting functions to be defined.



CONT (F1)

To confirm the changes and move to the previous screen.

EDIT (F3)

Edit parameters of current info page type. Refer to "7.5.1 Defining the Info Page Display" for more details.

PAGE (F6)

To go to the next page of the configuration.

Info Type

Defines the parameters to view on the Info page of the application. Different combinations of the parameters to view may be stored for the four main functions of the application: **Stake Face**, **Stake Profile**, **Check Profile**, **Scan Profile**.



For more information on the parameters that may be selected, refer to chapter "7.5.1 Defining the Info Page Display"

Plot configuration	Plot Type:	Defines the type of plot to be viewed on the Plot page. Cross Plot: View measured point with respect to design profile. Plan View: View position of measured point with respect to horizontal alignment. Profile View: View position of measured point with respect to vertical alignment.
	Pole Graphic:	Defines the graphical representation of the measured point on the plot page. Std Bitmap: Standard bitmap image of a reflector and pole. Actual Height: Reflector pole is not shown and position of reflector denotes the actual measured position.
	Update X-Sec:	Update frequency of the cross section view on the Plot page when working in tracking mode.
		0.5m or 2s: Update the plot every 2 seconds or when the measured point is more than 0.5 m from the previous plotted point. 0.5m or 10s: Update the plot every 10 seconds or when the measured point is more than 0.5 m from the previous plotted point. 1.0m or 30s: Update the plot every 30 seconds or when the measured point is more than 1 metre from the previous plotted point. 5.0m or 1m: Update the plot every 60 seconds or when the measured point is more than 5 metres from the previous plotted point.

Vertical Exg.:

Vertical exaggeration for cross section plots.

(Vertical plot scale relative to horizontal.)

0.5:	Ratio of vertical to horizontal scale 1:2
1:	Ratio of vertical to horizontal scale 1:1
2:	Ratio of vertical to horizontal scale 2:1
5:	Ratio of vertical to horizontal scale 5:1
10:	Ratio of vertical to horizontal scale 10:1

7.5.1 Defining the Info Page Display

Overview

The **Define Info Display** page allows the parameters to view on the **Info** page of the application to be defined. Different combinations of the parameters to view may be stored for the four main functions of the application:

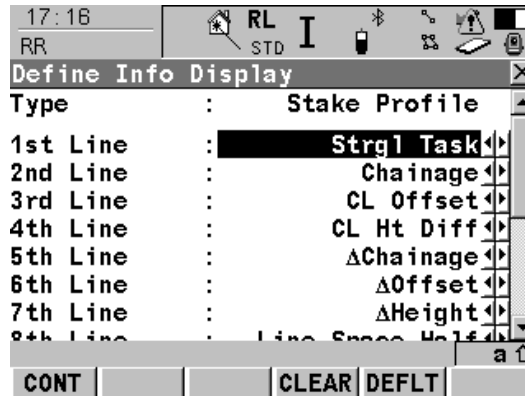
Stake Face, Stake Profile, Check Profile, Scan Profile.

The process for defining each of these combinations is identical. The user defines which parameter should be viewed on each line. Up to 16 lines of parameters may be defined although a maximum of 9 lines may be viewed at any one time.



Selecting the parameters

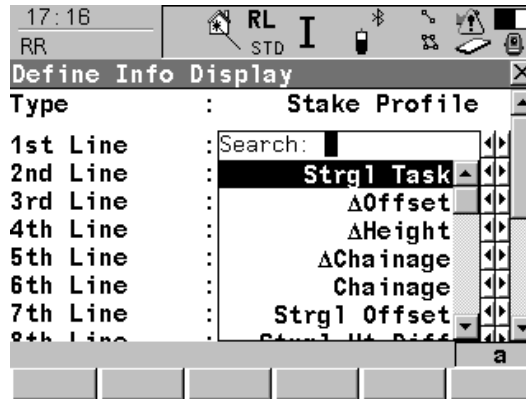
It is necessary to scroll with the arrow keys to view additional lines.



- CONT (F1)**
Confirm the changes and move to the previous screen.
- CLEAR (F4)**
Clear all parameters from all lines.
- DEFLT (F5)**
Set the default value for all lines.

To modify the selection on any particular line, place the cursor on the line to modify using the arrow keys and press the **ENTER** key.

Use the arrow keys to select the required parameter and press the **ENTER** key to confirm the choice. It is also possible to search for a parameter by entering the first character of the parameter name.



Available parameters

The following parameters are available in the Define Info Display:

Strgl Task:	Name of the current task.
ΔOffset:	Distance from the measured point to the point to set out in a direction perpendicular to the horizontal alignment.
ΔHeight:	Height difference between the measured point and the point to set out.
ΔChainage:	Chainage difference between the measured point and the point to set out.
Chainage:	Chainage of the measured point.
Strgl Offset:	Distance between the measured point and the shifted horizontal alignment when a shift is used.
Strgl Ht Diff:	Height difference between the measured point and the shifted vertical alignment when a shift is used.
Strgl Name:	Name of the centreline.
CL Ht Diff:	Height difference between the measured point and the height of the vertical alignment at the same chainage.
CL Height:	Height of the vertical alignment at the chainage of the measured point.
CL Radius:	Radius of the horizontal alignment at the at the chainage of the measured point.
CL Type:	Curve type of the horizontal alignment at the chainage of the measured point.
CL Offset:	Distance between the measured point and the horizontal alignment in a direction perpendicular to the horizontal alignment.
CL Tangent:	Direction of the tangent to the horizontal alignment at the at the chainage of the measured point.
Near Tang Pt:	Distance along the horizontal alignment from the measured point to the nearest tangent point.
CL Grade:	Grade of the vertical alignment at the chainage of the measured point.

Dirc to Point:	Direction from the point to the point to set out.
Dist to Point:	Distance from the point to the point to set out.
Def Easting:	Easting of the point to set out.
Def Northing:	Northing of the point to set out.
Def Height:	Height of the point to set out.
Act Easting:	Easting of the measured point.
Act Northing:	Northing of the measured point.
Act Height:	Height of the measured point.
Quality 3D:	Standard deviation of the point measurement.
Line Space	Empty line.
Half/Full	
Prof.Offset:	Distance from the design profile to the measured point.
Prof.N^oElement:	Element number of the closest design profile element to the measured point.
Prof.Element(%):	Distance in percentage terms of the measured point along the design profile element.
DistAlongProf:	Distance of the measured point along the design profile.
Vert Chainage:	Chainage of the measured point projected perpendicular to the vertical component of the centreline.
Vert Sqr Off:	Offset perpendicular to the vertical component of the centreline.

7.6 Tunnel Configuration Logfile Page

Logfile settings

The **Logfile** page allows the user to define the name and format of any logfile that should be written. Data is recorded to the logfile each time a data is recorded to the database. The format of the logfile is determined by the selected format file. Format files may be defined in the Format Manager component of the Leica Geo Office application.



CONT (F1)

To confirm the changes and move to the previous screen.

PAGE (F6)

To go to the next page of the configuration.

Write Logfile:

Defines whether a logfile should be written or not.

File Name:

Name of logfile to be written. Logfiles are stored in the folder named DATA on the CompactFlash card.

Format File:

Format file to use when writing the logfile.

Index

A

Act Easting	129
Act Height	129
Act Northing	129
Alignment	56
ALL	7, 39
Angular	46
Arrows&Graphics	115

B

Back Interval	43
Back interval	43
Bailout	14
Beep near Pt	120
Begin panel	30
Breakpoint	50

C

Centre Line	10
CL Grade	128
CL Height	128
CL Ht Diff	128
CL Offset	128
CL Radius	128
CL Tangent	128
CL Type	128
CH+1	70
Ch.Increment	70

Chain.Limit	53, 122
Chainage	6, 128
Chainage Tol	120
Check	6
Check Ht Diff	39
Check Offset	39
Check Profile	36
Clockwise	65
CompactFlash card	27
Constant	18
CONT	82
Control points	78
Converters	22
CounterClockwise	65
CProf.NºElement	129
Create	
Create	84
Creating a New Project	84
Creating a new task	95
Cross Plot	124

D

DBX	27
Define	
DChainage	128
Def Chainage	70
Def Easting	129
Def Height	129

Def Northing	129
Define	61
DEL	82
Deleting a Project	86
DHeight	128
Digital Terrain Model	80
Digital Terrain Models	78
Dirc to Point	129
Discrete points	50
Distance	
DIST	7, 39
Dist from Pt	120
Dist to Point	129
DistAlongProf	129
Distance	12, 43
DOffset	128
Downloads	22
DTM job	78
E	
EDIT	82
Editing a project	88
Element	65
Element&Offset	65, 73
End point	46
Error message	45
Exclude limit	47
Existing	82

F	
Face	6
Fixpoint job	78
Format	130
Format file	130
Format Manager	130
Forward	43
From Station	115
Fwd Distance	43
Fwd Interval	43
G	
General panel	45, 62
GET B	45
GET F	45
Graphics	115
Guidance	115
H	
Height Tol	120
Horizontal	56
I	
Include limit	47
Info Panel	67
Info Type	123
Info&Plot	39
Input Method	70
Iteration	59

J		Overbreak	10
Job	63	Overlapping zones	47
Jobs	78		
L		P	
LandXML	6	PAGE	7, 39
Layers	93	PAUSE	51
Licence key	28	Perpendicular	18
Limits	46	Plan View	124
Linear	18	Plane	46
Logfile	130	Plot	41
		Plot Type	124
M		Plumb line	18
Main menu	6	Point ID	38, 70
Max.Iterations	53, 122	Polar	115
Measurement job	78	Pole Graphic	124
MORE	82	Portal	10
		POSIT	65
N		Position Tol	120
Near Tang Pt	128	Profile	
NEW	61, 82	Prof.Element(%)	129
		Prof.Offset	129
O		ProfDist&Offset	64, 72
Off	115	Profile	6, 43, 120
Offset Tol	120	Profile Chain	43
Offset&Height	63, 71	Profile Tol	120
Offsets	11	Profile View	124
Option	56	Project Configuration	112
Orientation	115		
Orthogonal	115		

Q		
Quality 3D	129	
Quality Check	120	
R		
Rail Configuration	112	
REC	7, 39	
Reflector		
Refl Radius	117	
Reflector Ht	38	
reflector radius	41	
Reflectorless	41	
RESUM	83	
Road Configuration	112	
Road job	78	
RoadRunner Tunnel Setup panel.	36	
Rotation method	53, 122	
Rotation Point	10	
S		
Scan	15, 44	
Scan Mode	53, 122	
Scan Profile	36	
Selection	97	
Set out	56	
Shifts	17	
Sign convention	19	
Stake		
Stake	6	
Stake Height	71	
		Stake Height Difference
		63
		Stake Mode
		115
		Stake Offset
		63
		Stake Pt ID
		63, 71
		Starting point
		46
		STOP
		51
		Strgl Ht Diff
		128
		Strgl Name
		128
		Strgl Offset
		128
		Strgl Task
		128
		Stringline
		96
		Superelevation
		10
T		
Tangent	41	
Tight Behav.	122	
Tight Ignore	122	
Tight Toleran	122	
Tight tolerance	14	
To Alignment	115	
To Station	115	
Triangular Irregular Network	80	
Tunnel		
Tunnel Centreline	23	
Tunnel Configuration	112	
Tunnel Job	36, 78	

U

Underbreak	10
Update Angle	116
Update X-Sec	124

V

Vertical	56
Vertical exaggeration	125

W

Work Corridor	116
Working with shifts	99

Z

Zone	46
------------	----

Total Quality Management: Our commitment to total customer satisfaction.



Leica Geosystems AG, Heerbrugg, Switzerland, has been certified as being equipped with a quality system which meets the International Standards of Quality Management and Quality Systems (ISO standard 9001) and Environmental Management Systems (ISO standard 14001).

Ask your local Leica Geosystems dealer for more information about our TQM program.

Leica Geosystems AG
Heinrich-Wild-Strasse
CH-9435 Heerbrugg
Switzerland
Phone +41 71 727 31 31
www.leica-geosystems.com

- when it has to be **right**

Leica
Geosystems